

# PW4001

# **POWER ANALYZER**

4-channel compact power analyzer featuring:

DC & 50/60 Hz power accuracy ±0.03% of reading ±0.01% of range Wide operating temperature range from -20°C to +50°C (-4°F to 122°F)

Lightweight at 4.6 kg (162.26 oz.)

600 kHz measurement frequency band

2.5 MHz, 16-bit sampling performance

15 GB internal memory

CAN input/output functionality

AC power supply input from 100 to 240 V

DC power supply input from 10.8 to 28 V  $^{\ast 1}$ 

\*1 option







#### **Features**

- Easy power measurement with clamp current sensors
- · 4 voltage channnels and 4 current channels
- Accuracy of DC and 50/60 Hz that meets WLTP and SAE J1634 requirements
- Excellent environmental durability suitable for low-temperature testing of EVs and batteries (e.g., -10°C, -20°C, respectively)
- Weight: 4.6 kg(162.26 oz.), small and light enough to be held with one hand
- 15 GB internal memory for storing setting files, measured data, and screenshots
- · Measured data can be converted to CAN format and output, enabling easy data integration with CAN analysis software (CAN output function)
- CAN data and measured data can be saved simultaneously (CAN input function)
- CAN data can be acquired via vehicle diagnostic communication using OBD-II/OBDonUDS (CAN input function)
- Data can be saved at intervals as fast as 1 ms
- Simultaneous parallel calculation of all parameters such as RMS, harmonics, instantaneous waveforms, and efficiency

#### **Applications**

- Type approval testing to measure EV range (km), energy consumption (Wh/km), and fuel consumption (I/km)
- · EV's real drive testing
- Efficiency measurement on inverter/motor test bench
- Evaluation of transient power and torque response of motors
- Recharge/discharge energy measurement of ESSs (Energy Storage Systems)
- Efficiency measurement on DC-DC converter, AC-DC converter
- Input/output power measurement and efficiency evaluation of high-voltage power conditioners



# **POWER ANALYZER**

#### **Parts Names and Functions**

#### Front

#### Rear side



#### Left side



- Handle
- USB port
- 9 Current input terminals
- 13 USB port (mini-B type)

- Display area
- Voltage input terminals
- DC power supply (option: operates on 10.5 V to 28 V DC)
- 14 External control terminal

- 3 Control area
- Motor analysis (option)
- 11 Power supply inlet
- 15 BNC synchronization connector

- 4 Power key
- Waveform and D/A output (option)
- 12 RJ-45 connector
- 16 CAN/CAN FD connector

#### **Software**

#### **GENNECT One**

(free download software)

- Logging
- Dashboard · Remote control
- · File acquisition
- · Automatic data collection



Operating

Windows 11、Windows 10 (32-bit or 64-bit edition), Windows 8.1 (32-bit or 64-bit edition)

#### ■ PW Data Receiver

(free download software)

- · Measured data saving · Waveform data saving
- · Remote control · File acquisition



Windows 11(64-bit edition), Windows 10 (64-bit edition) Version 21H2 or later

#### CAN Editor(for PW)

(free download software)

- Setting up CAN input/output function
- CAN IDs can be set from CAN definition file (DBC file)



Windows 11(64-bit edition), Windows 10 (32-bit or 64-bit edition)

#### **Measurement System Construction**

#### LabVIEW Drivers and MATLAB Toolkit

Simple GUI operation on LabVIEW and the use of MATLAB functions allow you to quickly build your measurement system. (LabVIEW is a trademark of NATIONAL INSTRUMENTS CORP., MATLAB is a trademark of MathWorks, Inc.)





# **Basic Specifications**

Model		PW4001	PW3390
Appea	arance	MACON I  MAC	
	Measurement frequency band	DC, 0.1 Hz to 600 kHz	DC, 0.5 Hz to 200 kHz
	Basic accuracy for 50/60 Hz	± (0.03% of reading + 0.01% of range)	± (0.04% of reading + 0.05% of range)
	Accuracy for DC power	± (0.03% of reading + 0.01% of range)	± (0.05% of reading + 0.07% of range)
	Accuracy for 10 kHz power	± (0.2% of reading + 0.05% of range)	± (0.2% of reading + 0.1% of range)
	Accuracy for 50 kHz power	± (0.4% of reading + 0.1% of range)	± (0.4% of reading + 0.3% of range)
ည	Number of power measurement channels	4 channels	4 channels
Measurement parameters	Voltage, current ADC	16-bit, 2.5 MHz	16-bit, 500 kHz
para	sampling Voltage range	6 V, 15 V, 30 V, 60 V, 150 V, 300 V, 600 V, 1500 V	15 V, 30 V, 60 V, 150 V, 300 V, 600 V, 1500 V
nent	Current range	40 mA to 8000 A (6 ranges, based on sensor)	40 mA to 8000 A (6 ranges, based on sensor)
surer	Common-mode voltage	50 Hz/60 Hz: 80 dB or greater	50/60 Hz: 80 dB or greater
Меа	rejection ratio		
	Temperature coefficient	0.005%/°C	0.01%/°C
	Voltage input method	Isolated input, resistor voltage division	Isolated input, resistor voltage division
	Current input method	Isolated input from current sensor	Isolated input from current sensor
	External current sensor input  Power supplied to external	Yes (ME15W)	Yes (ME15W)
	current sensor	Yes	Yes
	Data update rate	1 ms, 10 ms, 50 ms, 200 ms	50 ms
voltage	Maximum input voltage  Maximum rated	AC 1000 V, DC 1500 V, ± 2000 V peak  AC 600 V/DC 1000 V CAT III	1500 V, ± 2000 V peak 600 V CAT III
5 .⊑	line-to-ground voltage	AC 1000 V/DC 1500 V CAT II	1000 V CAT III
Analysis	Number of motor analysis channels	Maximum 2 motors*1	1 motor*1
Ana	Motor analysis input format	Analog DC, frequency, pulse	Analog DC, frequency, pulse
	Current sensor phase shift calculation	Yes (Auto)	Yes
	Harmonics measurement	Yes (4 for each channel)	Yes
_	Maximum harmonics analysis order	500th	100th
Function	Harmonics synchronization	0.1 Hz to 600 kHz	0.5 Hz to 5 kHz
F	frequency range User-defined calculations	Yes	_
	Delta conversion	Yes (Δ-Y, Y-Δ)	Yes ( Δ -Y)
	D/A output	Yes*1 16ch (waveform output, analog output)	Yes*1 16ch (waveform output, analog output)
ay	Display	10.1" WXGA TFT color LCD	9" WVGA TFT color LCD
Display	Touch screen	Yes	-
_	External storage media	USB 3.0	USB 2.0, CF card
	LAN (100BASE-TX,	Yes	Yes
e	1000BASE-T) RS-232C	-	(10BASE-T and 100BASE-TX only)  Yes (maximum 38,400 bps)
Interface	External control	Yes	Yes
드	Synchronization of multiple	Yes (up to 8 instruments)	Yes (up to 8 instruments)
	instruments CAN or CAN FD	Yes	
)imor		361 mm (14.21 in.) × 176 mm (6.93 in.) × 135 mm (5.31 in.),	340 mm (13.39 in.) × 170 mm (6.69 in.) × 156 mm (6.14 in
ıınen	sions, weight (W × H × D)	4.6 kg (162.26 oz.)	4.6 kg (162.26 oz.)

\*1: Sold separately



# **Basic Specifications**

# Input specifications

(1) Voltage, current, and power measurement shared specifications				
No. of PW4001 input channels	Voltage 4 channels (U1 to U4) Current 4 channels (I1 to I4)			
Measurement lines	Single-phase 2-wire (1P2W) Single-phase 3-wire (1P3W) 3-phase 3-wire (3P3W2M, 3V3A, 3P3W3M) 3-phase 4-wire (3P4W)			
Measurement method	Voltage/current simultaneous digital sampling with zero-crossing synchronized calculation			
Sampling	2.5 MHz, 16-bit			
Measurement frequency band	DC, 0.1 Hz to 600 kHz			
Frequency flatness	$\pm$ 0.1% amplitude band: 50 kHz (typical) $\pm$ 0.1° phase band: 100 kHz (typical)			
Effective measurement range	Voltage, current, and active power For DC: 0% to 110% of the range For AC: 1% to 110% of the range			
Measurement modes	Wideband measurement mode			
Data update rate	1ms, 10 ms, 50 ms, 200 ms Average and user-defined operations are unavailable when the data update interval is set to 1 ms.			
	Cutoff frequency fc 500 Hz, 1 kHz, 5 kHz, 10 kHz, 100 kHz, OFF			
LPF	Add $\pm$ 0.05% of the reading to the accuracy except if the LPF is set to off. The accuracy specifications are specified for frequencies less than or equal to one tenth the set cutoff frequency. The peak value is based on the LPF-processed values, whereas the peak-over judgment			
	uses not-digital-LPF processed values.			
Synchronization source	U1 to U4, I1 to I4, DC (fixed at the data update interval for DC only)  PW4001-03、PW4001-05 only  Ext1 to 2, Zph1, CH B, D			
	Can be selected for each wiring configuration. (U and I of the same channel are measured in sync with the same synchronization source.)  The zero-crossing point of the waveform after passing through the zero-cross filter is used as the reference when U or I is selected.			
Synchronization source effective frequency range	DC, 0.1 Hz to 200 kHz			
Synchronization source effective input range	1% to 110% of range			
Zero-cross filter	Used in zero-crossing detection for voltage and current waveforms. Does not affect measured waveforms.  Consists of a digital LPF and HPF filters. Cutoff frequencies are automatically determined based on the settings of the measurement upper and lower frequency limits as well as measurement frequencies.  HPF is selectable between on and off.			
Lower measurement frequency limit	Choose from the following frequency values for each wiring configuration: 0.1 Hz, 1 Hz, 10 Hz, 100 Hz, 1 kHz, 10 kHz, 100 kHz			
Upper measurement frequency limit	Choose from the following frequency values for each wiring configuration: 100 Hz, 500 Hz, 1 kHz, 5 kHz, 10 kHz, 50 kHz, 100 kHz, 500 kHz, 1 MHz			
Polarity detection	Voltage/current zero-crossing timing comparison method			
Measurement parameters	Voltage (U), current (I), active power (P), apparent power (S), reactive power (Q), power factor (\(\lambda\)), phase angle (\(\phi\)), voltage frequency (IU), current frequency (II), efficiency (\(\eta\)), loss (Loss), voltage ripple factor (Urf), current ripple factor (Irf), current integration (Ih), power integration (WP), voltage peak (Upk), current peak (Ipk)			
(2) Voltage measurem				
Input terminal profile	Plug-in terminal (safety terminal)			
Input method	Isolated input, resistance voltage division			
Display range	RMS, DC: 0% to 150% of range (1500 V range: 0% to 135%) Waveform peak: 0% to 300% of range (1500 V range: 0% to 135%)			
Range	6 V, 15 V, 30 V, 60 V, 150 V, 300 V, 600 V, 1500 V			
Crest factor	3 relative to voltage range rating (however, 1.35 for 1500 V range)			
Input resistance, input capacitance	$3 \text{ M }\Omega\pm30 \text{ k }\Omega$ , $1 \text{ pF typical}$			
Maximum input voltage	1000 V AC, 1500 V DC or ± 2000 V peak			
Maximum rated line-to-ground voltage	600 V AC, 1000 V DC in measurement category III Anticipated transient overvoltage: 8000 V 1000 V AC, 1500 V DC in measurement category II Anticipated transient overvoltage: 8000 V			



(3) Cur	rent measurem	ent specifications			
Input terminal profile		Dedicated connector (ME15W)			
Input me		Current sensor input method			
Display	rango	RMS, DC: 0% to 150% of range			
Display	range	Waveform peak: 0% to 300% of range			
		2 A sensor : 40 mA, 80 mA, 200 mA, 400 mA, 800 mA, 2 A			
		20 A sensor : 400 mA, 800 mA, 2 A, 4 A, 8 A, 20 A			
		200 A sensor : 4 A, 8 A, 20 A, 40 A, 80 A, 200 A			
	Probe1:	2000 A sensor : 40 A, 80 A, 200 A, 400 A, 800 A, 2 kA			
	Automatically recognizes the sensor's rated current	5 A sensor : 100 mA, 200 mA, 500 mA, 1 A, 2 A, 5 A			
		50 A sensor : 1 A, 2 A, 5 A, 10 A, 20 A, 50 A 500 A sensor : 10 A, 20 A, 50 A, 100 A, 200 A, 500 A			
		5000 A sensor : 100 A, 20 A, 500 A, 1 kA, 2 kA, 5 kA			
_		1000 A sensor : 20 A, 40 A, 100 A, 200 A, 400 A, 1 kA			
Range		Selectable for each wiring			
		(Only when the same sensors are used for all channels of the same wiring configuration)			
		1 V/A : 40 mA, 80 mA, 200 mA, 400 mA, 800 mA, 2 A			
		100 mV/A : 400 mA, 800 mA, 2 A, 4 A, 8 A, 20 A			
	CT9920: The sensor	10 mV/A : 4 A, 8 A, 20 A, 40 A, 80 A, 200 A			
	output rate can	1 mV/A : 40 A, 80 A, 200 A, 400 A, 800 A, 2 kA			
	be selected	0.1 m A : 400 A, 800 A, 2 k A, 4 kA, 8 kA, 20 kA			
		Selectable for each wiring			
Croot to	otor	(Only when the same sensors are used for all channels of the same wiring configuration)			
Crest fa		3 relative to current range rating 1 M $\Omega$ ± 50 k $\Omega$			
	m input voltage	8 V, ± 12 V peak (10 ms or less)			
IVIAXIIII	iii iiipat voitage	Up to 4			
Maximu	m number of	Up to three CT6877A, CT6876A, or CT6904A series current sensors can be connected when using an AC or DC power supply (power supply voltage: 10.5 V to 20 V) and with an operating temperature of 40° C to 50° C.			
connect	ed channels				
		Up to three CT6877A, CT6876A, or CT6904A series current sensors can be connected when using a DC power supply (power			
		supply voltage: 20 V to 28 V) and with an operating temperature of 30° C to 40° C.			
(4) Fre	quency measur	ement ement			
Number	of measurement	4 channels (fU1 to fU4, fI1 to fI4)			
	ement method	Reciprocal method			
ivieasure		The waveforms processed with the zero-cross filter are measured.			
Measure	ement range	0.1 Hz to 500 kHz (The display shows 0.00000 Hz or Hz if measurement was not possible.)  The range is limited by the measurement lower frequency limit setting.			
		± 0.005 Hz			
		Assuming all the following conditions are met: • Measurement parameter: voltagefrequency			
		<ul> <li>Data update interval: 50 ms or more ◆ Voltage range: 15 V range or higher</li> <li>Inputted waveform: a sine wave with a magnitude of at least 50% of the range</li> </ul>			
Measure	ement accuracy	Frequency range: 45 Hz to 66 Hz			
		Under conditions other than listed above: ± 0.05% of the reading			
		(With a sine wave at least 30% of the measurement range of the measurement source. However, add $\pm$ 0.05 % of the reading for the data update interval of 1 ms.)			
D: .	1.00	0.10000 Hz to 9.99999 Hz, 9.9000 Hz to 99.9999 Hz, 99.000 Hz to 999.999 Hz, 0.99000 kHz to 9.99999 kHz,			
Display	resolution	9.9000 kHz to 99.9999 kHz, 99.000 kHz to 999.999 kHz			
(5) Inte	gration measu				
Measure	ement modes	Can be chosen between RMS and DC for each wiring.			
ivieasurement modes		(The DC mode is selectable for the 1P2W wiring configuration only.)			
		0 0 77			
Measure	ement parameters	Current integration (Ih+, Ih - , Ih), Active power integration (WP+, WP - , WP) The instrument measures Ih+ and Ih - only in DC mode; Ih only in RMS mode.			
Measure	ement parameters	Current integration (lh+, lh -, lh), Active power integration (WP+, WP -, WP) The instrument measures lh+ and lh - only in DC mode; lh only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.)			
	ement parameters	Current integration (lh+, lh -, lh), Active power integration (WP+, WP -, WP) The instrument measures lh+ and lh - only in DC mode; lh only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.) In DC mode: Integrates current values and instantaneous power values for each polarity at every sampling point.			
Measure	ement method	Current integration (lh+, lh -, lh), Active power integration (WP+, WP -, WP) The instrument measures lh+ and lh - only in DC mode; lh only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.) In DC mode: Integrates current values and instantaneous power values for each polarity at every sampling point. In RMS mode: Integrates current RMS values and active power values at the measurement intervals.			
Measure	<u> </u>	Current integration (lh+, lh -, lh), Active power integration (WP+, WP -, WP) The instrument measures lh+ and lh - only in DC mode; lh only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.) In DC mode: Integrates current values and instantaneous power values for each polarity at every sampling point. In RMS mode: Integrates current RMS values and active power values at the measurement intervals.  Same as the data update interval			
Measure	ement method	Current integration (lh+, lh -, lh), Active power integration (WP+, WP -, WP) The instrument measures lh+ and lh - only in DC mode; lh only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.) In DC mode: Integrates current values and instantaneous power values for each polarity at every sampling point. In RMS mode: Integrates current RMS values and active power values at the measurement intervals.			
Measure Measure Display	ement method	Current integration (lh+, lh-, lh), Active power integration (WP+, WP-, WP) The instrument measures lh+ and lh- only in DC mode; lh only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.)  In DC mode: Integrates current values and instantaneous power values for each polarity at every sampling point.  In RMS mode: Integrates current RMS values and active power values at the measurement intervals.  Same as the data update interval  999999 (6 digits + decimal point),			
Measure Measure Display Measure	ement method ement interval resolution ement range	Current integration (lh+, lh-, lh), Active power integration (WP+, WP-, WP) The instrument measures lh+ and lh- only in DC mode; lh only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.) In DC mode: Integrates current values and instantaneous power values for each polarity at every sampling point. In RMS mode: Integrates current RMS values and active power values at the measurement intervals.  Same as the data update interval  999999 (6 digits + decimal point), Starts from the resolution assuming 1% of each range to be 100% of the range.			
Measure Measure Display	ement method ement interval resolution ement range	Current integration (Ih+, Ih-, Ih), Active power integration (WP+, WP-, WP) The instrument measures Ih+ and Ih- only in DC mode; Ih only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.) In DC mode: Integrates current values and instantaneous power values for each polarity at every sampling point. In RMS mode: Integrates current RMS values and active power values at the measurement intervals.  Same as the data update interval  999999 (6 digits + decimal point), Starts from the resolution assuming 1% of each range to be 100% of the range.  0 Ah / Wh to ± 99.9999 PAh / PWh  0 s to 9999 h 59 min. 59 s Integration stops if the integration time exceeds the range.			
Measure Display Measure Integrati	ement method ement interval resolution ement range ion time ion time accuracy	Current integration (Ih+, Ih-, Ih), Active power integration (WP+, WP-, WP) The instrument measures Ih+ and Ih- only in DC mode; Ih only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.) In DC mode: Integrates current values and instantaneous power values for each polarity at every sampling point. In RMS mode: Integrates current RMS values and active power values at the measurement intervals.  Same as the data update interval  999999 (6 digits + decimal point), Starts from the resolution assuming 1% of each range to be 100% of the range.  0 Ah / Wh to ± 99.9999 PAh / PWh  0 s to 9999 h 59 min. 59 s Integration stops if the integration time exceeds the range.  ± 0.02% of reading (-20°C to 50°C)(-4° F to 122° F)			
Measure Display Measure Integrati	ement method ement interval resolution ement range ion time	Current integration (lh+, lh-, lh), Active power integration (WP+, WP-, WP) The instrument measures lh+ and lh- only in DC mode; lh only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.) In DC mode: Integrates current values and instantaneous power values for each polarity at every sampling point.  In RMS mode: Integrates current RMS values and active power values at the measurement intervals.  Same as the data update interval  999999 (6 digits + decimal point), Starts from the resolution assuming 1% of each range to be 100% of the range.  0 Ah / Wh to ± 99.9999 PAh / PWh  0 s to 9999 h 59 min. 59 s Integration stops if the integration time exceeds the range.  ± 0.02% of reading (-20°C to 50°C)(-4° F to 122° F)  ± (Current or active power) ± (Integration time accuracy)			
Measure Display Measure Integrati	ement method ement interval resolution ement range ion time ion time accuracy	Current integration (Ih+, Ih-, Ih), Active power integration (WP+, WP-, WP) The instrument measures Ih+ and Ih- only in DC mode; Ih only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.) In DC mode: Integrates current values and instantaneous power values for each polarity at every sampling point. In RMS mode: Integrates current RMS values and active power values at the measurement intervals.  Same as the data update interval  999999 (6 digits + decimal point), Starts from the resolution assuming 1% of each range to be 100% of the range.  0 Ah / Wh to ± 99.9999 PAh / PWh  0 s to 9999 h 59 min. 59 s Integration stops if the integration time exceeds the range.  ± 0.02% of reading (-20°C to 50°C)(-4° F to 122° F)			
Measure Measure Display Measure Integrati Integrati	ement method ement interval resolution ement range ion time ion time accuracy	Current integration (lh+, lh -, lh), Active power integration (WP+, WP -, WP) The instrument measures lh+ and lh - only in DC mode; lh only in RMS mode.  Digital calculation based on current and active power. (Calculations are performed using not-averaged values during averaging.) In DC mode: Integrates current values and instantaneous power values for each polarity at every sampling point. In RMS mode: Integrates current RMS values and active power values at the measurement intervals.  Same as the data update interval  999999 (6 digits + decimal point), Starts from the resolution assuming 1% of each range to be 100% of the range.  0 Ah / Wh to ± 99.9999 PAh / PWh  0 s to 9999 h 59 min. 59 s Integration stops if the integration time exceeds the range.  ± 0.02% of reading (-20°C to 50°C)(-4° F to 122° F)  ± (Current or active power) ± (Integration time accuracy)			



6) Harmonics measur	ement			
Number of measurement channels	Up to 4			
Synchronization source	Based on the synchronization source setting of the voltage, current, and power measurement selected for each wiring configuration.			
Measurement modes	Wideband measurement mode			
Measurement parameters	Harmonic voltage RMS value, harmonic voltage content percentage, harmonic voltage phase angle, harmonic current RMS value, harmonic current content percentage, harmonic current phase angle, harmonic active power, harmonic power content percentage, harmonic voltage-vscurrent phase difference, total harmonic voltage distortion, total harmonic current distortion, voltage unbalance rate, current unbalance rate			
FT processing word ength	32-bit			
Antialiasing	Digital filter (automatically set based on syn-	chronization frequency)		
Vindow function	Rectangular			
Grouping	OFF, Type 1 (harmonic sub-group), Type 2 (Setting common to all channels)	(harmonic group)		
ΓHD calculation method	THD_F, THD_R Select the calculation order from between 2 (Setting common to all channels)	nd and 500th. (However, limited to the maxin	mum analysis order of each mode.)	
7) Wideband measure	ement mode: wideband harmonic m	easurement		
Measurement method	Zero-crossing sync calculation method (the Fixed sampling interpolation calculation method)		rce), with gaps	
Synchronization frequency range	0.1 Hz to 600 kHz			
Data update rate	Fixed at 50 ms. When it is set to 10 ms, only harmonic data When it is set to 200 ms, values are obtained			
	Fundamental wave frequency	Window wave number	Maximum analysis order	
	$0.1 \text{ Hz} \leq f \leq 2 \text{ kHz}$	1	500th	
	2 kHz < f ≦ 5 kHz	1	300th	
	5 kHz < f ≦ 10 kHz	2	150th	
Maximum analysis order	10 kHz < f ≦ 20 kHz	4	75th	
nd Window wave number	20 kHz < f ≦ 50 kHz	8	30th	
	50 kHz < f ≦ 100 kHz	16	15th	
	100 kHz < f ≦ 200 kHz	32	7th	
	200 kHz < f ≦ 300 kHz	64	5th	
	300 kHz < f ≦ 500 kHz	128	3th	
	500 kHz < f ≦ 600 kHz	256	1th	
Phase zero-adjustment	Phase zero-adjustment can be started by using keys or communications commands.  (Only available when the synchronization source is set to Ext)  Phase zero-adjustment values can be set automatically or manually.  Valid setting range of the phase zero-adjustment: 0.000° to ± 180.000° (in 0.001° increments)			
No. of FFT points	Automatically selected from among 2048, 40	· · · · · · · · · · · · · · · · · · ·		
	Add the following values to the voltage, current, power, and phase difference accuracy. When the fundamental frequency is 100 Hz or more, add another $\pm$ 0.1% of the range to the following voltage, current, and power accuracies, and add $\pm$ 0.1° to the phase difference accuracy. When the fundamental frequency is 2 kHz or more, add another $\pm$ 0.05% of the reading and $\pm$ 0.1% of the range to the following voltage, current, and power accuracies, and add $\pm$ 0.1° to the phase difference accuracy.			
	Frequency	Voltage, current, power ± (% of reading)	Phase difference ± (°)	
	DC	0.05%	-	
	0.1 Hz ≦ f ≦ 100 Hz	0.01%	0.1°	
la a a cura a a a b a a a cura a c	100 Hz < f ≦ 1 kHz	0.03%	0.1°	
leasurement accuracy	1 kHz < f ≦ 10 kHz	0.08%	0.6°	
	10 kHz < f ≦ 50 kHz	0.15%	$(0.020 \times f) \pm 0.5^{\circ}$	
	50 kHz < f ≦ 200 kHz	0.20%	$(0.030 \times f) \pm 2.0^{\circ}$	
	<ul> <li>In the expressions listed above, the unit of</li> <li>The figures for voltage, current, power, an</li> <li>When the fundamental wave has a frequer phase difference over 6 kHz are values for</li> <li>When the fundamental wave has a frequer phase difference for frequencies other tha</li> <li>Accuracy values for phase difference are amplitude of at least 10% of the range.</li> </ul>	d phase difference for frequencies over 200 ncy within the range of 16 Hz to 850 Hz, the reference purposes. ncy outside the range of 16 Hz to 850 Hz, then the fundamental wave are values for reference.	figures for voltage, current, power, and e figures for voltage, current, power, and ence purposes.	



#### Measurement accuracy

Accuracy guarantee duration: 12 months

Accuracy guarantee conditions

(The accuracy guarantee duration for voltage, current, and power measurements, as well as for voltage accuracy of the motor analysis option, is either 6 months or 12 months. Accuracy is calculated by multiplying the reading error specified in each accuracy specification by 1.5.)

Accuracy guarantee temperature and humidity range: 23° C  $\pm$  3° C (73° F  $\pm$  5° F), 80% RH or less

Warm-up time: 30 minutes or longer
Other conditions: Within the effective measurement ranges, sine waveforms or DC input, a line-to-earth voltage of 0 V After zero adjustment has been performed and a change in ambient temperature does not exceed  $\pm$  1° C after zero adjustment.

Voltage (U) and Current (I)		
Accuracy	± (% of reading + % of range)	
DC	0.03% + 0.01%	
$0.1 \text{ Hz} \leq f \leq 30 \text{ Hz}$	0.10% + 0.20%	
30 Hz < f ≦ 45 Hz	0.10% + 0.10%	
45 Hz < f ≦ 440 kHz	0.03% + 0.01%	
440 Hz < f ≦ 1 kHz	0.05% + 0.05%	
1 kHz < f ≦ 10 kHz	0.20% + 0.05%	
10 kHz < f ≦ 50 kHz	0.40% + 0.10%	
50 kHz < f ≦ 100 kHz	0.01*f % + 0.20%	
100 kHz < f ≦ 200 kHz	0.025*f % + 0.30%	
Frequency Band	600 kHz (-3 dB typical)	

Active power (P) and Power phase angle ( φ )		
Accuracy	Active power (P)	Power phase angle (Φ)
Accuracy	± (% of reading + % of range)	0
DC	0.03% + 0.01%	_
$0.1 \text{ Hz} \leq f \leq 30 \text{ Hz}$	0.10% + 0.20%	± 0.05°
30 Hz < f ≦ 45 Hz	0.10% + 0.10%	± 0.05°
45 Hz < f ≦ 440 kHz	0.03% + 0.01%	± 0.05°
440 Hz < f ≦ 1 kHz	0.05% + 0.05%	± 0.05°
1 kHz < f ≦ 10 kHz	0.20% + 0.05%	± 0.20°
10 kHz < f ≦ 50 kHz	0.40% + 0.10%	± (0.02*f)°
50 kHz < f ≤ 100 kHz	0.01*f % + 0.20%	± (0.02*f)°
100 kHz < f ≦ 200 kHz	0.025*f % + 0.30%	± (0.02*f)°

- Unit for "f" in accuracy calculations as mentioned in the table above: kHz
- · Voltage and current DC values are defined for Udc and Idc, while frequencies other than DC are defined for Urms and Irms
- When U or I is selected as the synchronization source, accuracy is defined for source input of at least 5% of range
   Power phase angle accuracy is defined at a power factor of zero with 100% input.
- Add the current sensor accuracy to the above accuracy figures for current, active power, and phase difference.
- The accuracy figures for voltage, current, active power, and phase difference for 0.1 Hz ≤ f < 10 Hz are reference values.</li>
   The accuracy figures for voltage, active power, and phase difference in excess of 220 V from 10 Hz ≤ f < 16 Hz are reference values.</li>
- The accuracy figures for voltage, active power, and phase difference in excess of 1000 V from 16 Hz ≤ f < 30 kHz are reference values
- The accuracy figures for voltage, active power, and phase difference in excess of 750 V from 30 kHz < f ≤ 100 kHz are reference values.</li>
   The accuracy figures for voltage, active power, and phase difference in excess of (22000/f [kHz]) V from 100 kHz < f ≤ 1 MHz are reference values.</li>
   For the voltage 6 V range, add ± 0.02% of range to voltage and active power accuracy.

- For the voltage 15 V range, add ± 0.005% of range to voltage and active power accuracy.
  When using probe 1 and the sensor's rated 1/25 and 1/50 range, add ± 0.02% of range to current and active power accuracy.
  When using probe 1 and the sensor's rated 1/10 range, add ± 0.01% of range to current and active power accuracy.
- The effective measurement range of the current sensor (9272-05, CT7642, CT7742, CT7044, CT7045, CT7046) is between 0.5% of full scale and 100% of full scale.
   When measuring DC 1000 V or greater, add ± 0.05% of reading to voltage and active power accuracy.
   When 100% of range < input ≤ 110% of range, range error × 1.1.</li>

- If a voltage is over 600 V, add the following values to the power phase angle accuracy:
  0.1 Hz < f ≤ 500 Hz ± 0.1°, 500 Hz < f ≤ 5 kHz ± 0.3°, 5 kHz < f ≤ 20 kHz ± 0.5°, 20 kHz < f ≤ 200 kHz ± 1°</li>
  A dd the following value to the accuracy figures for voltage and active power if a voltage of 600 V or more is measured.

- $\pm$  (0.003 × V^2)% of the reading  $\pm$  (1 × V^2) mV (V is input voltage [kV]) Even when the voltage input value decreases, the effect of self-heating persists until the input resistance temperature drops. If the input voltage is over 900 V, other measurement channels (up to 600 V) will also have half the influence.
- If zero adjustment is performed with a warm-up time of less than 60 minutes, add  $\pm$  0.02% of the range to the voltage, current, and active power accuracy
- $\cdot$  W hen the data update interval is 1 ms, add  $\pm$  0.1% of the range to the voltage, current, and active power accuracy.

Apparent power (S) Measurement accuracy	(voltage accuracy) + (current accuracy) ± 10 digits
Reactive power (Q) Measurement accuracy	For any condition except if $\varphi=0^\circ$ or $\pm$ 180° (Apparent power accuracy) $\pm$ $\{1-\sin[\varphi+(Power phase angle accuracy)] / \sin\varphi\} \times (100% of the reading) \pm [\sqrt{(1.001-\lambda 2)}-\sqrt{(1-\lambda 2)]} \times (100% of the range) For \varphi=0^\circ and \pm 180° (Apparent power accuracy) \pm [\sin(Power phase angle accuracy)] \times (100% of the range) \pm (3.16% of the range) The symbol \lambda designates the display value of the power factor.$
Power factor (λ) Measurement accsuracy	For any condition except if $\phi = \pm 90^\circ$ $\pm \{1 - \cos[\phi + (\text{Power phase angle accuracy})] / \cos \phi\} \times (100\% \text{ of the reading}) \pm 50 \text{ digits}$ For $\phi = \pm 90^\circ$ $\pm \cos[\phi + (\text{Power phase angle accuracy})] \times (100\% \text{ of the range}) \pm 50 \text{ digits}$ The symbol $\phi$ designates the display value of the power phase angle. Both of the above are specified at voltage/current range rating input.
Waveform peak measurement acuracy	Voltage and current RMS value accuracy ± 1% of the range (300% of the range is applied as a peak range)
Effects of temperature	Add $\pm$ 0.005% of the reading/° C to the voltage, current, and active power accuracy within the range of $-20^{\circ}$ C to $20^{\circ}$ C or $26^{\circ}$ C to $50^{\circ}$ C.  Add $\pm$ 0.005% of the range/° C to DC accuracy of the voltage, current, and active power if a change in operating temperature range reaches or exceeds $\pm$ 1° C after zero adjustment.  For the 6 V range, add another $\pm$ 0.005% of the reading/° C to the DC accuracy of the voltage, current and active power.





Common-mode rejection ratio (effects of commonmodevoltage)	50 Hz/60 Hz: 80 dB or more Specified for CMRR when the maximum input voltage is applied between the voltage input terminals and the enclosure for all measurement ranges.
Effects of external magnetic fields	± 1% of the range or less (in a magnetic field of 400 A/m, DC or 50 Hz/60 Hz)
Effects of power factor on active power	For any condition except if $\phi = \pm 90^{\circ}$ $\pm \{1 - \cos[\phi + (\text{Phase accuracy})] / \cos \phi\} \times (100\% \text{ of the reading})$ For $\phi = \pm 90^{\circ}$ $\pm \cos[\phi + (\text{Phase accuracy})] \times (100\% \text{ of VA})$
Effect of conducted radio frequency electromagnetic field	For current and active power measurement, 6% of full scale or less at 10 V Current full scale means the sensor's rated current Active power full scale means the voltage range × current sensor rating
Effect of radiated radio frequency electromagnetic field	For current and active power measurement, 6% of full scale or less at 10 V/m Current full scale means the current sensor rating Active power full scale means the voltage range × current sensor rating

# **Waveform recording**

Number of measurement channels	Voltage and current waveforms: Up to 4 channels (up to 8 waveforms can be displayed) Motor waveform: Up to 2 analog DC channels + up to 4 pulse channels		
Recording capacity	(5 megawords) × [(Number of measured items, including voltage and current) × (Number of channels, up to 4) + (Number of channe		
Waveform resolution	16-bit		
Sampling speed	Voltage and current waveform  Motor waveform (analog DC)*  (1 MS/s is interpolated with 0th held when 2.5 MS/s of data is sampled.)  Motor waveform (pulse)*  2.5 MS/s, 1.0 MS/s, 500 kS/s, 250 kS/s, 100 kS/s, 50 kS/s, 25 kS/s, 10 kS/s		
Recording length	1 kiloword, 5 kilowords, 10 kilowords, 50 kilowords, 100 kilowords, 500 kilowords, 1 megaword, 5 megawords		
Storage mode	Peak-to-peak compression		
Trigger mode	SINGLE / NORMAL(auto-trigger setting available)		
Pre-trigger	0% to 100% of the recording length, in 10 percent increments		
	Level trigger (detects triggers based on fluctuations in the level of storage waveforms)     Trigger source: Voltage and current waveforms, voltage and current waveforms processed by the zero-cross filter, manual trigger, motor waveform, motor pulse     Trigger slope: Rising edge, falling edge     Trigger level: ± 300% of the range for waveforms in 0.1 percent increments		
Trigger detection method	• Event trigger  Triggers are detected based on fluctuations in the values of basic measurement items.  The trigger-detecting conditions are determined based on the logical OR and AND of the following four events. The logical AND takes precedence over the logical OR.  Events: Composed of basic measurement items, inequality signs (<, >), and numerical values (0 to ± 99999.9T).  Ev n:Item   X.XXXXX y  (n: 1 to 4, Item: basic measurement item,   : inequality signs, X.XXXXX: six-digit constant, y: SI prefix)		

<sup>\*</sup>PW4001-03 and -05 models with motor analysis option only.



# Motor Analysis (Option)

(PW4001-03, -05 only)

<u> </u>		nput shared specification	s			
	4 channels					
Number of input channels		Channel		Input parameter		
rambor or impat orial molo		CH A, CH C	Ar	nalog DC, frequency, pulse		
	CH B, CH D Frequency, pulse					
	Motor analys	sis mode				
		Measurement or dete	ection item (input type)	Maximum number of analysis parameters		
	Pattern 1	Torque(Analog/F	reg), Speed(Pulse)	2 motors		
	Fallelli	, , ,	req), Speed(Pulse),	2 ITIOLOIS		
	Pattern 2		eq), speed(Fulse), Origin(Pulse)	1 motor		
Operating mode	Pattern 3		Speed(Pulse), Direction	1 motor		
	Pattern 4	1 1 0 0	peed(Pulse), Origin(Pulse)	1 motor		
	Pattern 5	1 1 0 17-1	eq), Speed(Analog)	1 motor		
	Individual inc	Individual input mode				
	Ch. A, Ch. C: DC voltage measurement, frequency measurement Ch. B, Ch. D: Frequency measurement					
nput terminal profile	Isolated BNC	Connector				
nput method		lated input and single-end input				
<u> </u>		annels function isolation				
nput resistance (DC)	1 M Ω ± 50 F	KΩ				
Maximum input voltage	20 V					
Maximum rated line-to- ground voltage	30 V (50 Hz /	/ 60 Hz)				
Measurement parameters	Voltage torg	que, RPM, frequency, slip, motor	nower			
Synchronization source	0 , 1		<u> </u>	ecifications" in the basic specifications		
Lower measurement		among the following frequency v	•	·		
frequency limit		, 10 Hz, 100 Hz				
Upper measurement frequency limit		among the following frequency v Hz, 1 kHz, 5 kHz, 10 kHz, 50 kH				
Input frequency source		etween fU1 to fU4 and fI1 to fI4.				
No. of motor poles	2 to 254					
Z-phase pulse detection reference	The reference for detecting Zph of the synchronization source can be set in operating mode 2 or 4. Rising edge, falling edge					
(2) Analog DC input (0		0 0				
Measurement range	1 V, 5 V, 10 V	V				
Crest factor	1.5					
Effective input range	1% to 110%	of range				
Sampling	1 MHz, 16-bi	it				
LPF	1 kHz / OFF	(20 kHz)				
Response speed	0.2 ms (when	n the LPF is disabled)				
Measurement method	Simultaneous digital sampling, zero-crossing synchronization calculation method			thod		
			synchronization calculation me			
	(Between-zer	ro-crossing averaging)	synchronization calculation me			
	(Between-zer ± 0.03% of r	ro-crossing averaging) reading ± 0.03% of range				
Measurement accuracy Effects of temperature	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ±	ro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem	ange of -20° C to 20° C or 26° C	to 50° C.		
Measurement accuracy  Effects of temperature  Effects of commonmode	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t	ro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n	to 50° C. nore after zero adjustment.		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage	(Between-zer $\pm$ 0.03% of r Add $\pm$ 0.005 Also, add $\pm$ $\pm$ 0.01% of t When a volta	ro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n	to 50° C. nore after zero adjustment.		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of the	ro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input termi	to 50° C. nore after zero adjustment.		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of the	ro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is he range or less ic field of 400 A/m, DC or 50 Hz/	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input termi	to 50° C. nore after zero adjustment.		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range	(Between-zer $\pm$ 0.03% of r Add $\pm$ 0.005 Also, add $\pm$ $\pm$ 0.01% of th When a volta $\pm$ 0.1% of th (in a magneti 0 to $\pm$ 150% For torque: $\pm$	pro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less the range or less to field of 400 A/m, DC or 50 Hz/60 to 0.01 to 9999.99	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input termi	to 50° C. nore after zero adjustment.		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range	(Between-zer $\pm$ 0.03% of r Add $\pm$ 0.005 Also, add $\pm$ $\pm$ 0.01% of th When a volta $\pm$ 0.1% of th (in a magneti 0 to $\pm$ 150% For torque: $\pm$ For RPM: $\pm$ 0	pro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less the range or less tic field of 400 A/m, DC or 50 Hz/60  ± 0.01 to 9999.99 0.00001 to 99999.9	range of -20° C to 20° C or 26° C perature changes of $\pm$ 1° C or n applied between the input terming (60 Hz)	to 50° C. nore after zero adjustment. inals and the enclosure		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± 0 Scaled input When the tor	ro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less ic field of 400 A/m, DC or 50 Hz/60 ± 0.01 to 9999.99 0.00001 to 99999.9 coffsets less than or equal to ± que meter correction is enabled	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input terming (60 Hz)	to 50° C. nore after zero adjustment. inals and the enclosure ted for to zero.		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± 0 Scaled input When the tor adding the co	ro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is he range or less ic field of 400 A/m, DC or 50 Hz/  ± 0.01 to 9999.99 0.00001 to 9999.99 coffsets less than or equal to ± reque meter correction is enabled halibration values.	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input terming (60 Hz)	ito 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero.		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± 0 Scaled input When the tor adding the coordinates	pro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less the range or less to field of 400 A/m, DC or 50 Hz/60  ± 0.01 to 9999.99 0.00001 to 99999.9 c offsets less than or equal to ± que meter correction is enabled railbration values. electable by motor) y correction	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input terming (60 Hz)  10% of the range are compensated.	to 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero. to zero after		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: 5 Caled input When the toradding the c: 0 FF/ON (se Nonlinearity Torque value	pro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less dic field of 400 A/m, DC or 50 Hz/ b ± 0.01 to 9999.99 0.00001 to 9999.99 c offsets less than or equal to ± r que meter correction is enabled calibration values. electable by motor) y correction as are corrected using an 11-poi	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input terming (60 Hz)  10% of the range are compensated.	ito 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero.		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: 5 Caled input When the toradding the c: 0 FF/ON (se Nonlinearity Torque value	pro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less the range or less to field of 400 A/m, DC or 50 Hz/60  ± 0.01 to 9999.99 0.00001 to 99999.9 c offsets less than or equal to ± que meter correction is enabled railbration values. electable by motor) y correction	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input terming (60 Hz)  10% of the range are compensated.	to 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero. to zero after		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of th When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± 0 Scaled input When the tor adding the c: OFF/ON (se Nonlinearity Torque value calibration va	pro-crossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less ic field of 400 A/m, DC or 50 Hz/60  ± 0.01 to 9999.99 0.00001 to 9999.99 0.00001 to 99999.9 coffsets less than or equal to ± reque meter correction is enabled ralibration values. electable by motor) y correction as are corrected using an 11-poi alues (N • m).	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input terming (60 Hz)  10% of the range are compensated, input offsets are compensated at a maximum) correction taken	to 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero. to zero after  ple of torque calibration points (N • m) vs. torque		
Measurement accuracy Effects of temperature Effects of commonmode voltage Effects of external magnetic fields Display range Scaling Zero-adjustment	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± 0 Scaled input When the tor adding the coordinate of	recorossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less dictified of 400 A/m, DC or 50 Hz/60 ± 0.01 to 9999.99 0.00001 to 99999.9 offsets less than or equal to ± distallibration values. electable by motor) y correction es are corrected using an 11-poi alues (N • m).	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input termi (60 Hz)  10% of the range are compensated, input offsets are compensated int (at a maximum) correction tabulat (at a maximum) correction tabulated (at a maximum) correction	to 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero. to zero after  ple of torque calibration points (N • m) vs. torque		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling  Zero-adjustment	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± 0 Scaled input When the tor adding the coordinate of	recorossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less ric field of 400 A/m, DC or 50 Hz/60 ± 0.01 to 9999.99 0.00001 to 9999.99 coffsets less than or equal to ± rque meter correction is enabled calibration values. electable by motor) y correction as are corrected using an 11-poi alues (N • m).	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input termi (60 Hz)  10% of the range are compensated, input offsets are compensated int (at a maximum) correction tabulat (at a maximum) correction tabulated (at a maximum) correction	to 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero. to zero after  ple of torque calibration points (N • m) vs. torque		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling  Zero-adjustment	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± 0 Scaled input When the tor adding the coordinate of	recorossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less dic field of 400 A/m, DC or 50 Hz/60 ± 0.01 to 9999.99 0.00001 to 99999.9 coffsets less than or equal to ± que meter correction is enabled dialibration values. electable by motor) y correction se are corrected using an 11-poi alues (N • m).  rection se are corrected using an 11-poi alues (N • r I between torque calibration value the correction table depends on	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input termination of the range are compensated, input offsets are compensated int (at a maximum) correction table, it (at a	to 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero. to zero after  ple of torque calibration points (N • m) vs. torque		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling  Zero-adjustment	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± ( Scaled input When the tor adding the color of	recorocssing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less ric field of 400 A/m, DC or 50 Hz/60 ± 0.01 to 9999.9 0.00001 to 99999.9 0.00001 to 99999.9 0.offsets less than or equal to ± range or less calibration values. electable by motor) y correction es are corrected using an 11-poi alues (N • m).  rection es are corrected using an 11-poi alues (N • m).  rection the correction value (N • r I between torque calibration value the correction table depends on git calibration value.	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input terming (60 Hz)  10% of the range are compensated, input offsets are compensated ant (at a maximum) correction taken).  Int (at a maximum) correction taken).	to 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero. to zero after  ple of torque calibration points (N • m) vs. torque  ple of RPM values (r/min.) with consideration of rotation		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling  Zero-adjustment	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± ( Scaled input When the tor adding the calibration value calibration value calibration value to Friction cor Torque value calibration value to Friction cor Torque value to Horizon value calibration value to Horizon value to Friction cor Torque value to Horizon value to Hori	recorocssing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less cic field of 400 A/m, DC or 50 Hz/  ± 0.01 to 9999.9 0.00001 to 99999.9 offsets less than or equal to ± raque meter correction is enabled calibration values. electable by motor) y correction es are corrected using an 11-poi alues (N · m).  restince to reque calibration values (N · r I between torque calibration value the correction table depends on git calibration value. torque calculation are used for or	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input terming (60 Hz)  10% of the range are compensate, input offsets are compensated ant (at a maximum) correction taken).  Interest (at a maximum) correction taken).	to 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero. to zero after  ple of torque calibration points (N • m) vs. torque		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling  Zero-adjustment	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± 0 Scaled input When the ton adding the c. OFF/ON (se Nonlinearity Torque value calibration va • Friction cor Torque value directions vs Each interval The unit for tig Enter a 6-dig The signs of OFF	recorossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less ic field of 400 A/m, DC or 50 Hz/60  ± 0.01 to 9999.99 0.00001 to 9999.99 0.00001 to 9999.99 coffsets less than or equal to ± r rque meter correction is enabled alibration values. electable by motor) y correction as are corrected using an 11-poi alues (N · m).  rrection es are corrected using an 11-poi alues (N · m).  rrection the correction table depends on git calibration value. torque calculation are used for c : (Torque value) = S × [X - (Ze  (Torque value)]	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input termination of the range are compensated, input offsets are compensated and (at a maximum) correction table, in the compensation of the setting.  The setting of the range are compensated and the setting of the sett	to 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero. to zero after  ple of torque calibration points (N • m) vs. torque  ple of RPM values (r/min.) with consideration of rotation		
Measurement accuracy Effects of temperature Effects of commonmode voltage Effects of external magnetic fields Display range Scaling Zero-adjustment  Torque meter correction	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± 0 Scaled input When the tor adding the c: OFF/ON (se • Nonlinearly Torque value directions vs Each interval The unit for tt Enter a 6-dig The signs of OFF ON S	reactions averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less die field of 400 A/m, DC or 50 Hz/60 ± 0.01 to 9999.99 0.00001 to 9999.99 0.00001 to 9999.99 1. offsets less than or equal to ± 1. offsets less than	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input terming (60 Hz)  10% of the range are compensated in the compensated in t	to 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero. to zero after  ple of torque calibration points (N • m) vs. torque  ple of RPM values (r/min.) with consideration of rotation		
Measurement accuracy  Effects of temperature  Effects of commonmode voltage  Effects of external magnetic fields  Display range  Scaling  Zero-adjustment	(Between-zer ± 0.03% of r Add ± 0.005 Also, add ± ± 0.01% of t When a volta ± 0.1% of th (in a magneti 0 to ± 150% For torque: ± For RPM: ± ( Scaled input When the tor adding the c:  OFF/ON (se Nonlinearity Torque value calibration va  Friction cor Torque value directions vs Each interval  The unit for tt Enter a 6-dig The signs of OFF ON S X	recorossing averaging) reading ± 0.03% of range 5% of the reading/° C within the r 0.005% of the range/° C for tem the range or less age of 30 V (DC, 50 Hz/60 Hz) is the range or less ric field of 400 A/m, DC or 50 Hz/60  ± 0.01 to 9999.99 0.00001 to 9999.99 0.00001 to 9999.99 0.00001 to sea the readily of the readily o	range of -20° C to 20° C or 26° C perature changes of ± 1° C or n applied between the input terming (60 Hz)  10% of the range are compensated in the compensated in t	to 50° C. nore after zero adjustment.  inals and the enclosure  ted for to zero. to zero after  ple of torque calibration points (N • m) vs. torque  ple of RPM values (r/min.) with consideration of rotation		



(3) Frequency input (0	CH A, CH B, CH C, CH D)		
Detection level	Low: approx. 0.8 V or less; High: approx. 2.0 V or more		
Measurement frequency band	0.1 Hz to 2 MHz (when the duty ratio is set at 50%)		
Minimum detection width	0.25 µs or more		
Measurement range	The zero-point frequency fc and frequency fd at rated torque in fc $\pm$ fd (Hz) can be set. Set fc and fd using 7-digit figures in the range of 1 kHz to 500 kHz. However, values must be set so that both the inequalities (fc + fd) $\leq$ 500 kHz and (fc - fd) $\geq$ 1 kHz are met.		
Measurement accuracy	$\pm$ 0.01% of the reading When the data update interval is set to 1 ms, add $\pm$ 0.01% of the reading to the measuring accuracy.		
Display range	1.000 kHz to 500.000 kHz		
Scaling	± 0.01 to 9999.99		
Zero-adjustment	Offsets of input within the range of fc ± 1 kHz can be compensated to zero.  When the torque meter correction is ON, calibration values are added to compensate for offsets to zero.		
Units	mN · m, N · m, kN · m		
Torque meter correction	Same as torque meter correction with analog DC input		
Torque calculations and correction	Same as torque meter correction with analog DC input		
(4) Pulse input (CH A,	CH B, CH C, CH D)		
Detection level	Low: approx. 0.8 V or less; High: approx. 2.0 V or more		
Measurement frequency band	0.1 Hz to 2 MHz (when the duty ratio is set at 50%)		
Minimum detection width	0.25 µ s or more		
Pulse filter	OFF / Weak / Strong positive/negative pulses of less than 0.25 $\mu$ s are ignored with the Weak setting, as are those less than 5 $\mu$ s with the Strong setting)		
Measurement range	2 MHz		
Measurement accuracy	$\pm$ 0.01% of reading When the data update interval is set to 1 ms, add $\pm$ 0.01% of the reading to the measuring accuracy.		
Display range	0.1 Hz ~ 2.00000 MHz		
Units	Hz, r/min		
Frequency division setting range	± 1 to 60000		
Rotation direction detection	Individually settable in [A-D] Pattern 2 to Pattern 5 of motor analysis mode Detects direction based on lead/lag of Ch. B and Ch. C in [A-D].		
Mechanical angle origin detection	Individually settable in [A-D] Pattern 2 to Pattern 5 of motor analysis mode Ch. B frequency division is cleared at the Ch. D rising or falling edge in [A-D].		

### Waveform & D/A output (Option)

### (PW4001-02, 05 only)

Number of output channels	16 channels
Output terminal profile	D-sub 25-pin connector × 1
Output details	Switchable between waveform output and analog output (selectable from basic measurement)
D/A conversion resolution	16-bit (polarity + 15 bits)
Output refresh rate	Waveform output: 1 MHz Analog output: 1 ms, 10 ms, 50 ms, 200 ms (depending on data update intervals of selected items, with an error of ± 1 ms)
Output voltage	Waveform output: Switchable between $\pm$ 2 V f.s. and $\pm$ 1 V f.s., crest factor: 2.5 or more The settings affect all channels. Analog output: $\pm$ 5 V DC f.s. (approx. up to $\pm$ 12 V DC)
Maximum output voltage	Approx. ± 12 V
Output resistance	100 Ω± 5 Ω
Output accuracy	Waveform output: Add $\pm$ 0.5% f.s. to measurement accuracy with the $\pm$ 2 V f.s. setting. Add $\pm$ 1.0% f.s. to measurement accuracy at the $\pm$ 1 V f.s. setting. Specified assuming DC to 50 kHz output. Analog output: Add $\pm$ 0.2% f.s. to the measurement accuracy of output measurement items (DC level).
Temperature coefficient	± 0.05% f.s. / °C

# Display section

Display characters	Japanese, English, Simplified Chinese, Traditional Chinese
Display	10.1" WXGA TFT color LCD (1280 × 800 dots)
Dot pitch	0.1695 (V) mm × 0.1695 (H) mm
Display value resolution	999999 count (including integrated values)
Display refresh rate	Measured values: Approx. 200 ms (independent of internal data update interval) Waveforms: Based on waveform recording settings
Screens	Measurement screen, Input Settings screen, System Settings screen, File Operation screen
Warning display	When an input-channel voltage or current peak-over condition is detected, when no synchronization source is detected. Warning icons for all channels will be displayed on any page of the screen.



### Instrument controls

Control devices	Power button × 1, rubber keys × 23, rotary knobs × 2, touchscreen
Touch panel	Analog resistive film
File operations	Displaying data list stored on a USB flash drive, formatting a USB flash drive, creating new folders, renaming folders/files, copying/deleting files, updating the firmware, displaying screenshots, creating/loading settings files

# **External interface**

(1) USB flash drive in	terface		
Connector	USB Type A receptacle connector X 1		
Electrical specifications	USB 3.0 (SuperSpeed)		
Connected device	USB flash drive		
Recorded data	Saving/loading settings files Saving measured values and automatically recorded data Saving waveform data and screenshots		
(2) LAN interface			
Connector	RJ-45 connector × 1		
Electrical specifications	IEEE 802.3 compliant		
Transmission method	100Base-TX, 1000Base-T (automatic detection)		
Protocol	TCP/IP (with DHCP function)		
Functions	HTTP server (remote operation) Dedicated port (data transfer, command control) FTP server (file transfer) FTP client Modbus/TCP server XCP on Ethernet (compliant with ASAM e.V.MCD-1 v 1.5.0)		
Recommended cable	Category 6A or higher STP cable, max. cable length 5 m		
(3) USB (function)			
Connector	Series Mini B receptacle × 1		
Electrical specifications	USB2.0 (Full Speed / High Speed)		
Class	Proprietary (USB488h)		
Connected device	Computer (Windows 10 (32-bit, 64-bit) / Windows 11 (64-bit)		
Functions	Data transfer, command control, USB mass storage LAN cannot be used simultaneously. If connected simultaneously, the USB connection will take priority.  Operation and communication are not possible during USB mass storage		
(4) External control in	terface		
Connector	4-terminal screwless terminal block × 1		
Pin assignments	No. 1 pin: Ground No. 2 pin: Data reset No. 3 pin: Hold No. 4 pin: Start/stop		
Electrical specifications	Logic signal of 0 / 5 V (2.5 V to 5 V) or contact signals by shorting/opening the terminal		
Functions	Same operation as the START/STOP key, DATA RESET key, or HOLD key on the control panel		
(5) BNC sync. interfac	pe		
Connector	BNC		
Number of instruments that can be synchronized	8 (one primary and seven secondary)		
Functionality	Primary instrument Transmitting control signals to secondary instruments Secondary instruments Synchronizing the following functions and operations with those of the primary instrument • Timing of internal calculations and data updating • Starting and stopping integration and resetting integration data • Freezing displays (HOLD/PEAK HOLD) and updating data during the display freeze • Zero adjustment • Operating the instrument using the SAVE and SCREEN SHOT keys • Present time (Synchronizable items cannot be controlled; their settings cannot be change during synchronization)  The primary and secondary instruments can synchronize only when they have the same settings of the measurement mode and data update interval; those with a data update interval of 10 ms or less cannot.		



(6) CAN/CAN FD inter	ace			
Protocol	CAN (classical) CAN FD (in conformity with ISO 11898-1:2015) CAN FD (not in conformity with ISO)			
Functionality	Data output Data input			
CAN ports	1 port			
CAN transceiver	MCP2544 FD			
Communications	D-sub 9-pin connector (r	nale)		
connector	Locking screw (hexagonal pillar): Inch screw #4-40 UNC			
Common data I/O settings	Baud rate	CAN 125 k, 250 k, 500 k, 1 Mbps  CAN FD  Arbitration area: 500 k, 1 M bps  Data area: 500 k, 1 M, 2 M, 4 M bps		
	Sample point setting	0.0% to 99.9%		
	Terminal resistance	ON/OFF Resistance value: 120 Ω±	= 10 Ω	
	ISO15765-2	ON/OFF		
	Data frame output	Continuous		
	Output interval	1 ms, 10 ms, 50 ms, 100 ms, 200 ms, 500 ms, 1 s, 5 s, 10 s, 15 s, 30 s, 1 min, 5 min, 10 min, 15 min, 30 min, 60 min  With an error of $\pm$ 1 ms from each data update interval setting  However, the interval cannot be set to less than the data update interval.		
Data output settings	Dan and all and a dan dan and	The output interval of 500 ms is unavailable with the data update interval of 200 ms.		
rata output settings	Repeated output count	0 to 10000 (0: infinite)		
	Format	Standard, extended		
	Setting ID	Standard fomat: 0x000 to 0x7FF Extended format: 0x00000000 to 0x1FFFFFFF		
	Data conversion	Measured data: Floating-point type (IEEE Float: 4 bytes) Output count, output time: Unsigned integer		
	Byte order (Endianness)	·   · · · · · · · · · · · · · · · · · ·		
	Number of receiving channels: Up to 20			
		Format	Standard / Extended	
		ID	Standard format: 0x000 to 0x7FF Extended format: 0x00000000 to 0x1FFFFFFF	
		Name		
	Desciving shapped	Unit		
	Receiving channel definition	Factor / offset		
		Start bit	0 to 5119 (bit)	
		Bit length	1 to 64 (bit)	
		Data type	Unsigned integer/signed integer/single-precision floating-point/doubleprecision floating-point	
S		Byte order	Motorola (big)/Intel (little)	
ata input settings	No. of transmitted arbitrary frames: Up to 20			
		Cyclic transmission	ON/OFF	
	Arbitrary frame transmission definition	Cyclic transmission interval	10 ms, 50 ms, 200 ms, START, STOP	
		Format	Standard / extended	
		ID	Standard format: 0x000 to 0x7FF Extended format: 0x00000000 to 0x1FFFFFFF	
		DLC(ISO15765-2 OFF)	CAN: 0 to 8 bytes CAN FD (ISO-compliant / ISO-non-compliant): 0 to 8 bytes, 12, 16, 20, 24, 32, 48, 64 bytes	
		Bit length (ISO15765-2 ON)	0 to 41 bytes	
		Transmitted data	Entered in hexadecimal	



# **Functional specifications**

# **AUTO-range function**

	The voltage and current ranges for each wiring configuration are automatically switched in response to the input. (excluding motor input ranges)
Operating mode	OFF / ON (selectable for each wiring configuration)

# Time control function

Functions	Other functions are controlled based on the time. Timer control, real time control
Operation	Timer control: Stops once the set amount of time has elapsed.  Real time control: Starts at the specified time and stops at the specified time.
Timer control	OFF, 1 s to 9999 h 59 m 59 s (in 1 s increments)
Actual time control	OFF, start time, stop time (in 1 s increments)

# **Hold function**

(1) Hold	
Functions	Stops updating display of all measured values, freezing the presently on-screen figures.  However, updating continues for waveforms, the clock, and on-screen peak-over conditions.  Internal calculations, for example integration and averaging, continue.  Cannot be used in combination with the peak hold function.
Output data	Hold data is output for analog output and save data during hold operation.  However, waveform output continues.
(2) Peak hold	
Functions	The display is updated by replacing all measured values with the maximum values obtained by comparing the absolute values for each measured value.  However, the waveform display and integrated values continue to be updated by being replaced with instantaneous data.  During average operation, the maximum value affects values measured after averaging.  Cannot be used in combination with the hold function.
Output data	Peak hold data is output for analog output and save data during peak hold operation.  However, waveform output continues.

# Calculation function

(1) Rectifier				
Functions	The voltage and current values used to calculate apparent and reactive power and power factor can be selected.			
Operating mode	rms / mean (Can be	e selected for each wiring configu	ration's voltage and current.)	
(2) Scaling				
Functions	The VT ratio and CT	ratio can be set so that they car	affect measured values.	
VT (PT) ratio		Can be set for each wiring configuration. 0.00001 to 9999.99 (The settings cannot be configured such that (VT × CT) is greater than 1.0E+06.)		
CT ratio	Can be set for each channel. 0.00001 to 9999.99 (The settings cannot be configured such that (VT × CT) is greater than 1.0E+06.)			
(3) Averaging (AVG)				
Functions	All instantaneous measured values, including harmonics, are averaged. (except peak values, integrated values, and harmonic data updated every 10 ms. When the data update rate is set to 1 ms, all averaging is not performed.)			
Operating mode	Off, exponential ave	Off, exponential average, moving average		
	Averaging count	FAST	MID	SLOW
	10 ms	0.1 s	0.8 s	5 s
	50 ms	0.5 s	4 s	25 s
Exponential averaging	200 ms	2.0 s	16 s	100 s
response rate	These values indicate the time required for the final stabilized value to converge on the range of $\pm$ 1% when the input changes from 0% to 90% of the range.  Although harmonic data is not averaged when the data update interval is set at 10 ms, harmonic data contained in basic measurement items is averaged using the exponential average coefficient every 10 ms. The speed is fixed in IEC measurement mode.			
No. of moving average iterations	2, 4, 8, 16, 32, 64 times			



(4) Efficiency and los	s calculations			
Functions	The efficiency $\eta$ (%) and loss (W) of each channel are calculated between wiring configurations' active power values.			
Calculated items	Active power value (P), fundamental wave active power (Pfnd), motor power (Pm), and userdefined formula (UDF) of each channel and wiring configuration			
Number of calculations that can be performed	Four for each efficiency and loss			
Modes	Fixed mode: In the case of items set on the input and output sides, the position in the equation is fixed, regardless of the measured value.  Auto mode: In the case of items set on the input and output sides, the position in the equation changes according to the positive and negative of the measured value.			
Equations	Fixed mode:  Calculation items can be substituted for Pin(n) and Pout(n).  Pin = Pin1 + Pin2 + Pin3 + Pin4 + Pin5 + Pin6  Pout = Pout1 + Pout2 + Pout3 + Pout4 + Pout5 + Pout6  η = 100 ×  Pout  /  Pin , Loss =  Pin  -  Pout   Auto mode:  Pin = (Sum of the absolute values of the positive parameter of the input and that of the negative parameter of the input)  Pout = (Sum of the absolute values of the positive parameter of the output and that of the negative parameter of the input)  η = 100 ×  Pout  /  Pin , Loss =  Pin  -  Pout			
(5) User-defined calc				
Functions	Calculates specified equations into which set basic measurement items are substituted.  No calculation can be performed if the data update interval is set to 1 ms.			
	Basic measurement items or 16 terms of constants with up to 6 digits, where the operators are the four fundamental operations UDFn = ITEM1 $\square$ ITEM2 $\square$ ITEM3 $\square$ ITEM4 $\square$ $\square$ ITEM16			
Calculation terms	ITEMn: Basic measurement items (including UDFn) or constants of up to six digits  The □ characters indicate one of the following operators: plus sign (+), minus sign (-), multiplication sign (*), and division sign (/)  ITEMn functions:  Neg (negative sign), sin, cos, tan, abs, log10 (common logarithm), log (logarithm), exp, sqrt, asin, acos, atan, sqr			
	Equations UDFns are calculated in the order of letters n; if a letter n on the right-hand side of an equation is more than that on the left-hand side, the previously calculated value is substituted.			
Number of equations	20 (UDF1 to UDF20)			
Maximum value setting	Set Fixed or Auto for each UDFn. Fixed: Can be set within the range of 1.000 n to 999.999 T. Auto: The first 6 digits are always displayed. (effective display range: 0 to ± 999.999 Y) The maximum value operates as a range of the UDFn.			
UDF name and units	Up to 8 ASCII characters per UDFn			
Integration	OFF/Positive/Negative/Total Can be set for each UDFn Off: Displays the calculated value of the UDFn. Positive: Displays the integrated value of the polarity (+) of the UDFn calculation value in UDFn. Negative: Displays the integrated value of the polarity (-) of the UDFn calculation value in UDFn. Total: Displays the integrated value of the UDFn equation in UDFn. (effective display range: 0 to ± 999.999 Y) Other values are not added if the integrated value exceeds the effective display range.			
(6) Delta conversion				
(o) Bena conversion	Δ-Y When using a 3P3W3M or 3V3A wiring method, it converts the line voltage waveform to a phase voltage waveform using a virtual neutral point.			
Functions	When using a 3P4W wiring method, it converts the phase voltage waveform to a line voltage waveform. Voltage RMS values and all voltage parameters, including harmonics, are calculated using the post-conversion voltage. However, peak-exceeded events are judged using pre-conversion values.			
(7) Power formula se	ection			
Functions	Equations for reactive power, power factor, and power phase angle can be selected.			
Formula	Type 1, Type 2, Type 3 Type 1: Compatible with the Type 1 for each of the PW3390, 3193 and 3390. Type 2: Compatible with the Type 2 for each of the 3192 and 3193. Type 3: The active power's sign can be used as the power factor's sign. (Type 1, Type 2, and Type 3 are compatible with each equation of the PW8001, PW6001.)			
(8) Current sensor pl	ase shift calculation			
Functions	Current sensor harmonic phase characteristics can be compensated using calculations.			
Operating modes	OFF / ON / AUTO (set for each channel) Automatic mode can be selected when a current sensor with the automatic recognition function is connected.			
Compensation value settings	Compensation points can be set using frequencies and phase differences. Frequency: 0.1 kHz to 5000.0 kHz (in 0.1 kHz increments) Phase difference: 0.000° to ± 180.000° (in 0.001° increments) The compensation value is automatically set when the current sensor is connected in the automatic operation mode.			
Max. correction range	Approx. 60 µs			
(9) Voltage probe pha				
Functions Operating modes	Voltage probes harmonic phase characteristics can be compensated using calculations.			
Operating modes  Compensation value settings	OFF / ON (can be set for each channel)  Compensation points can be set using frequencies and phase differences.  Frequency: 0.1 kHz to 5000.0 kHz (in 0.1 kHz increments)			
Max. correction range	Phase difference: 0.000° to ± 180.000° (in 0.001° increments)  Approx. 60 μ s			
	η Αμγιολ. ου μο			



# Display function

(1) Wiring method	confirmation screen		
Functions	Wiring diagrams as well as vector diagrams of voltage and current (for wiring configurations other than the singlephase wiring configuration only) can be displayed based on the selected measured line patterns. The on-screen vector diagram shows the vector ranges for correct connections, enabling the operator to check for proper connections.		
Mode at startup	The setting can be made so that the instrument always show the wiring configuration confirmation screen at startup (startup screen setting).		
Simple settings	Settings can be switched over those appropriate for objects under measurement selected for each wiring configuration. 50/60 Hz, DC/WLTP, PWM, HIGH FREQ, GENERAL.		
(2) Vector display	screen		
Functions	The screen can display wiring-specific vector graphs along with associated level values and phase angles.  The display orders and vector magnification can be selected.		
Display patterns	1-vector-diagram: Vectors can be drawn for up to four channels. 2-vector-diagram, 4-vector-diagram: Vectors can be drawn for each selected wiring configuration.		
(3) Numerical disp	play screen		
Functions	The screen can display measured power values and motor values for up to four installed channels.		
Display patterns	Basic display for each wiring configuration: The screen can display measured values of the lines under measurement and motors connected to the instrument. In addition to the four patterns, U, I, P, and Integ as well as motor is available. On-screen values are linked to the channel indicators.		
	Selective display:  The screen can display values of any measurement items selected from all basic measurement items at any positions.  There are 8-, 16-, 36-, and 64-display patterns available.		
(4) Harmonic disp	lay screen		
Functions	The screen can display measured harmonic values.		
Display patterns	Bar-graph display: The screen can display measured harmonic items for user-specified channels as bar graphs. (up to 500th) List display: The screen can display numerical values for user-specified parameters of user-specified channels.		
(5) Waveform dis	play screen		
Functions	The screen can display the motor waveform as well as the voltage and current waveforms.		
Display patterns	All-waveform display Waveform+numerical value display Zoom-display cursor measurement supported		

# Trend graph function

Functions	Displays a graph of measured values selected as output parameters in a time series.  The waveform is plotted by compressing the data at the data update interval using peak-topeak compression based on the time axis setting, and without the data being stored
Operation	Use the START/STOP key to start or stop plotting. Display values are plotted during hold or peak hold. Plotted data can be cleared by pressing the DATA RESET key after stopping using the STOP key, or by changing the time axis setting.
Plotted items	Up to 8 items
Time axis	50 ms/div to 24 h/div, plotting area: 20 div
Vertical axis	Auto scale (adjusts to fit data within the time axis display range within the screen), Manual (maximum and minimum display values are set by the user)

# Automatic data save function

Functions	Saves the user-specified measured values every user-specified interval		
Auto-save control	OFF/ON		
Save destination	USB flash drive, internal memory (capacity approx.: 15 GB) Select the media to be used for saving when auto-save control is on. If there is no USB flash drive, saving will take place on the internal memory. A folder created on a USB flash drive or in the internal memory can be specified as the destination to save data.		
Saved parameters	Selectable from all measured values, including measured harmonic values.  Harmonic readings are not saved automatically when the interval is set to 1 ms.		
Interval	OFF, 1 ms, 10 ms, 50 ms, 100 ms, 200 ms, 500 ms, 1 s, 5 s, 10 s, 15 s, 30 s, 1 min, 5 min, 10 min, 15 min, 30 min, 60 min However, the interval cannot be set to less than the data update interval.		
Max. savable data	Approx. 500 MB per file (automatically segmented) × 1000 files		
Data format	CSV: Measured data is delimited with commas (,) and periods (.) represent decimal points. SSV: Measured data is delimited with semicolons (;) and commas (,) represent decimal points. BIN: Common file-format that can be loaded by GENNECT One		
Filename	Automatically generated based on the time and date at which measurement started.		



#### Manual data save function

Manual data s	ave fullotion				
(1) Measurement d	ata				
Functions	Pressing the SAVE key can save values measured at the moment.  The data is outputted to the same file until the setting is changed, or the DATA RESET key is pressed.				
Save destination	USB flash drive, internal memory				
Saved parameters	Selectable from all measured values, including measured harmonic values.				
Max. save data	500 MB per file (automatically segmented)				
Data format	CSV, SSV				
(2) Waveform data					
Functions	When the Save button is tapped on the waveform screen of the touchscreen, the waveform is saved in the specified format.				
Save destination	USB flash drive, internal memory				
Saved parameters	Waveform data on the waveform screen				
Max. save data	Approx. 400 MB (in binary format) Approx. 2 GB (in text format)				
Data format	CSV, SSV, BIN, MAT				
(3) Screenshots					
Functions	Pressing the SCREEN SHOT key can save the screen displayed at the moment in PNG format.  Setting list screenshot function  Comment entering function  Free drawing function				
Save destination	USB flash drive, internal memory, FTP server				
Saved parameters	Screenshot data				
Data format	PNG				
(4) Settings data					
Functions	Saves various settings information as settings files using the [FILE] screen. In addition, loading a settings file saved using the [FILE] screen can restore settings. However, the language and communications settings are not restored. Settings data can be opened with the image viewer because it is inserted into an image that displays a settings list.				
Save destination	USB flash drive, internal memory, FTP server				
Saved parameters	Setting data				
Data format	SET				
(5)CAN output sett	ings data				
Functions	Data-output settings can be saved as DBC-files using the [CAN] screen.				
Save destination	USB flash drive, internal memory, FTP server				
Saved parameters	Output settings data				
Data format	DBC				
(6) User-defined eq	uation data				
Functions	User-defined formulas can be saved as JSON files using the [UDF] screen.  Loading a JSON file saved using the [UDF] or [FILE] screen can restore the equations.  Calculation is not possible if the loaded equations include calculation items that are invalid (items that cannot be selected according to the module, option configuration, or other setting).  ([] is displayed)				
Save destination	USB flash drive, internal memory, FTP server				
Saved parameters	User-defined formula				
Data format	JSON				



### Other functions

Clock function	Auto-calendar, automatic leap-year detection, 24-hour clock
Actual time accuracy	When the instrument is turned on: $\pm$ 100 ppm When the instrument is turned off: Within $\pm$ 3 s/day (at 25° C)
Sensor identification	Current sensors connected to input modules can be identified automatically.  The instrument can detect sensor ranges and the connection/disconnection of sensors, displaying warning dialog boxes.  Data compensation values provided by current sensors affect phase compensation data.
Zero suppression function	Selectable between OFF and ON. ON: $0.01 \sim 1.00$ % of full scale When this function is ON, values of measurement items less than the set value are replaced with zero.

# **Environment and safety specifications**

Operating environment	Indoor use, pollution level 2, altitude up to 2000 m
Operating temperature and humidity	-20° C to 50° C (-4° F to 122° F), 80% RH or less (after warm-up, non-condensing)  If used at temperatures below 0° C (32° F), warm up in a 0° C to 50° C (32° F to 122° F) environment prior to use.
Storage temperature and humidity	-20° C to 50° C (-4° F to 122° F), 80% RH or less (non-condensing)
Standards	Safety EN61010 EMC EN 61326 Class A
Vibration resistance	JIS D 1601:1995 5.3 (1) Type 1: Passenger cars, Condition: Equivalent to Type A Vibration acceleration: 45 m/s2 (4.6 G) for 4 h in the X direction and 2 h in the Y and Z directions
Power supply	Commercial power supply Rated supply voltage: 100 V to 240 V AC (Assuming voltage fluctuation of ± 10%) Rated power-supply frequency: 50 Hz, 60 Hz Anticipated transient overvoltage: 2500 V Maximum rated power: 120 VA Typical power consumption (reference value): 47 W (Conditions: Power supply voltage of 100 V/60 Hz. Voltage of 800 V DC and current of 200 A DC (CT6834) measured on all channels.)  DC power supply (optional) Rated supply voltage: 10.5 V to 28 V DC (Operating temperature range: - 20° C to 40° C) 10.5 V to 20 V DC (Operating temperature range: 40° C to 50° C) Maximum rated power: 95 VA
Backup battery life	Lithium battery About 10 years (Reference value at 23° C) Time and setting conditions
Dimensions	$361 \pm 2$ (W) $\times$ 176 $\pm$ 2 (H) $\times$ 135 $\pm$ 2 (H) mm (14.21 $\pm$ 0.08 (W) $\times$ 6.93 $\pm$ 0.08 (H) $\times$ 5.31 $\pm$ 0.08 (D) in) (excluding protruding parts)
Weight	Approx. 4.6 kg (162.26 oz.) (for PW4001-05)
Product warranty period	3 years



# High-accuracy clamp current sensors

clamp current sens	ors	Product warranty per	iod: 3 year Guaranteed acci	uracy period: 1 year (CT6831, CT6830	) Produc	ct warranty period: 1 year Guaranteed	d accuracy period: 1 year (CT6	6834, CT6834-01, CT6833, CT6833-01	
Model	C.	T6831	B31 CT6830		CT6834, CT6834-01		CT6833	CT6833, CT6833-01	
Appearance	nearance		NEW		NEW		NEW		
Rated current	20 .	A AC/DC	2	A AC/DC	50	00 A AC/DC	200	0 A AC/DC	
Frequency band	DC t	o 100 kHz	DC	to 100 kHz	DO	C to 50 kHz	DC	to 50 kHz	
Diameter of measurable conductors	Мах. ф 5	mm (0.20 in.)	Мах. ф	5 mm (0.20 in.)	Мах. ф	20 mm (0.79 in.)	Max. φ 2	20 mm (0.79 in.)	
PW4001 Combined Current (I)), Active power (P)	PW4001 accura	acy + Sensor accuracy	PW4001 accur	racy + Sensor accuracy	DC 45 Hz ≦ f ≦ 66Hz	: ± 0.1% ± 0.02%*1 : ± 0.1% ± 0.017%*1	DC 45 Hz ≦ f ≦ 66Hz	: ± 0.1% ± 0.02%* <sup>1</sup> : ± 0.1% ± 0.017%* <sup>1</sup>	
_	DC	: ± 0.3% ± 0.10%	DC	: ± 0.3% ± 0.10%	DC	: ± 0.07% ± 0.01%	DC	: ± 0.07% ± 0.01%	
Sensor only (amplitude)*2	DC < f ≤ 66 Hz	: ± 0.3% ± 0.01%	DC < f ≤ 66 Hz	: ± 0.3% ± 0.05%	DC < f < 16 Hz	: ± 0.15% ± 0.01%	DC < f < 16 Hz	: ± 0.15% ± 0.01%	
and a	66 Hz < f ≤ 500 Hz	: ± 0.3% ± 0.02%	66 Hz < f ≤ 500 Hz	: ± 0.3% ± 0.05%	16 Hz ≤ f ≤ 66 Hz	: ± 0.07% ± 0.007%	16 Hz ≤ f ≤ 66 Hz	: ± 0.07% ± 0.007%	
Sensor only (amplitude)*2		: ± 0.5% ± 0.05%	500 Hz < f ≤ 1 kHz	: ± 0.5% ± 0.05%	66 Hz < f ≤ 100 Hz	: ± 0.07% ± 0.007%	66 Hz < f ≤ 100 Hz	: ± 0.07% ± 0.007%	
		: ± 1.0% ± 0.10%	1 kHz < f ≤ 5 kHz	: ± 1.0% ± 0.10%	100 Hz < f ≤ 500 Hz	: ± 0.1% ± 0.01%	100 Hz < f ≤ 500 Hz	: ± 0.1% ± 0.01%	
		: ± 5.0% ± 0.10%	5 kHz < f ≤ 10 kHz	: ± 5.0% ± 0.10%	500 Hz < f ≤ 1 kHz	: ± 0.25% ± 0.02%	500 Hz < f ≤ 1 kHz	: ± 0.25% ± 0.02%	
	10 kHz < f ≤ 100 kHz	: ± 30% ± 0.10%	10 kHz < f ≤ 100 kHz	: ± 30% ± 0.10%	1 kHz < f ≤ 20 kHz	: ± (0.25% × 1)% ± 0.02%		: ± (0.25% × 1)% ± 0.029	
Common-Mode Rejection Ratio (CMRR)	130 dB or grea	ater (DC to 100 Hz) ter (100 Hz to 1 kHz) e and common mode voltage)	125 dB or gre	eater (DC to 100 Hz) ater (100 Hz to 1 kHz) ge and common mode voltage)	130 dB or gre 120 dB or gre	greater (DC to 1 kHz) eater (1 kHz to 10 kHz) ater (10 kHz to 50 kHz) ge and common mode voltage)	130 dB or gre 120 dB or grea	reater (DC to 1 kHz) ater (1 kHz to 10 kHz) ater (10 kHz to 50 kHz) ge and common mode voltage)	
Frequency derating	7x: Ambient temperature  30 A (-40°C≤ 7x≤+50°C)  20 A (-40°C≤ 7x≤+50°C)  20 A (-40°C≤ 7x≤+50°C)  DC  Frequency [Hz]		Sum y   10   3 A (-40°C≤7.≤+6   10   10   10   10   10   10   10   1		700 Derating	g (1 minute) g (1 minute) g (continuous), guaranteed accuracy range	0 DC 1 10	ontinuous) accuracy range  100 1k 10k 100k Frequency [Hz]	
Output voltage	0.1 V/A	(= 2 V/20 A)		1 V/A	4 mV/A			10 mV/A	
Operating temperature and humidity*3	80% Relay box: -25° C to	85° C (-40° F to 185° F), RH or less 5 50° C (-77° F to 122° F), RH or less	Sensor: -40° C to 85° C (-40° F to 185° F), 80% RH or less Relay box: -25° C to 50° C (-77° F to 122° F), 80% RH or less		809 Relay box: -25° C	C to 85° C (-40° F to 185° F), % RH or less to 50° C (-13° F to 122° F), % RH or less	80% Relay box: -25° C	C to 85° C (-40° F to 185° F), 6 RH or less to 50° C (-13° F to 122° F), 6 RH or less	
Storage temperature and humidity*3		and relay box: f to 122° F), 80% RH or less		and relay box: F to 122° F), 80% RH or less		r and relay box: 'F to 122° F), 80% RH or less		and relay box: F to 122° F), 80% RH or less	
Standards	Safety: EN 610	10, EMC: EN 61326	Safety: EN 61	010, EMC: EN 61326	Safety: EN 6	1010, EMC: EN 61326	Safety: EN 61	010, EMC: EN 61326	
Cable length	Between relay box to ou	y box: approx. 4 m (13.12 ft.) httput connector: approx 0.2 m 0.66 ft.)	Between sensor to relay box: approx. 4 m (13.12 ft.)			(16.40 ft.) including relay box m (32.81 ft.) including relay box		(16.40 ft.) including relay box m (32.81 ft.) including relay box	
Dimensions	(approx. 3.00 V Relay box: Approx. 8	W × 23.4 H × 14.2 D mm V × 0.92 H × 0.56 D in.) 0 W × 20 H × 26.5 D mm V × 0.79 H × 1.04 D in.)	Sensor: Approx. 76.5 W × 23.4 H × 14.2 D mm (approx. 3.00 W × 0.92 H × 0.56 D in.) Relay box: Approx. 80 W × 20 H × 26.5 D mm (approx. 3.15 W × 0.79 H × 1.04 D in.)		(approx. 5.87 W Relay box: approx.	49 W × 4 6H × 16.5 D mm V × 1.81 H × 0.65 D in.) 126 W × 57 H × 20.5 D mm V × 2.24 H × 0.81 D in.)	(approx. 5.87 W Relay box: approx. 1	9 W × 46 H × 16.5 D mm × 1.81 H × 0.65 D in.) 126 W × 57 H × 20.5 D mm × 2.24 H × 0.81 D in.)	
Weight	Approx. 1	60 g (5.64 oz.)	Approx.	160 g (5.64 oz.)		prox. 500 g (17.64 oz.) pprox. 710 g (25.05 oz.)		rox. 500 g (17.64 oz.) prox. 710 g (25.05 oz.)	

\*1: ± (% of reading + % of range) , range is PW4001 \*2: ± (% of reading + % of full scale) , full scale is rated current of sensor \*3: Non-condensing



<b>High-accuracy</b>	clamp	current	sensors
,			

Product warranty period: 3 year Guaranteed accuracy period: 1 year

Model	CT6846A	CT6845A	CT6844A	CT6843A	CT6841A	
Appearance	9					
Rated current	1000 A AC/DC	500 A AC/DC	500 A AC/DC	200 A AC/DC	20 A AC/DC	
Frequency band	DC to 100 kHz	DC to 200 kHz	DC to 500 kHz	DC to 700 kHz	DC to 2 MHz	
Diameter of measurable conductors	Max. φ 50 mm (1.97 in.)	Max. φ 50 mm (1.97 in.)	Max. φ 20 mm (0.79 in.)	Max. φ 20 mm (0.79 in.)	Мах. ф 20 mm (0.79 in.)	
PW4001 Combined*1	DC : ± 0.23% ± 0.03%	DC : ± 0.23% ± 0.03%	DC : ± 0.23% ± 0.03%	DC : ± 0.23% ± 0.03%	DC : ± 0.23% ± 0.06%	
Current (I)), Active power (P)	$45$ Hz $\leq$ f $\leq$ 66Hz : $\pm$ 0.23% $\pm$ 0.02%	$45$ Hz $\leq$ f $\leq$ 66Hz : $\pm$ 0.23% $\pm$ 0.02%	$45$ Hz $\leq$ f $\leq$ 66Hz : $\pm$ 0.23% $\pm$ 0.02%	45Hz ≤ f ≤ $66$ Hz : ± $0.23%$ ± $0.02%$	$45Hz \le f \le 66Hz$ : $\pm 0.23\% \pm 0.02\%$	
	DC : ± 0.2% ± 0.02%	DC : ± 0.2% ± 0.02%	DC : ± 0.2% ± 0.02%	DC : ± 0.2% ± 0.02%	DC : ± 0.2% ± 0.05%	
	DC < f ≤ 100 Hz : ± 0.2% ± 0.01%	DC < f ≤ 100 Hz : ± 0.2% ± 0.01%	DC < f ≤ 100 Hz : ± 0.2% ± 0.01%	DC < f ≤ 100 Hz : ± 0.2% ± 0.01%	DC < f ≤ 100 Hz : ± 0.2% ± 0.01%	
>	100 Hz < f ≤ 500 Hz : ± 0.5% ± 0.02%	100 Hz < f ≤ 500 Hz : ± 0.3% ± 0.02%	100 Hz < f ≤ 500 Hz : ± 0.3% ± 0.02%	100 Hz < f ≤ 500 Hz : ± 0.3% ± 0.02%	100 Hz < f ≤ 500 Hz : ± 0.3% ± 0.02%	
Sensor only (amplitude)*2	500 Hz < f ≤ 1 kHz : ± 1.0% ± 0.02%	500 Hz < f ≤ 1 kHz : ± 0.5% ± 0.02%	500 Hz < f ≤ 1 kHz : ± 0.5% ± 0.02%	500 Hz < f ≤ 1 kHz : ± 0.5% ± 0.02%	500 Hz < f ≤ 1 kHz : ± 0.5% ± 0.02%	
<u> </u>	1 kHz < f ≤ 5 kHz : ± 2.0% ± 0.02%	1 kHz < f ≤ 5 kHz : ± 1.0% ± 0.02%	1 kHz < f ≤ 5 kHz : ± 1.0% ± 0.02%	1 kHz < f ≤ 5 kHz : ± 1.0% ± 0.02%	1 kHz < f ≤ 5 kHz : ± 1.0% ± 0.02%	
Sensor only (amplitude)*2	5 kHz < f ≤ 10 kHz : ± 5.0% ± 0.02%	5 kHz < f ≤ 10 kHz : ± 1.5% ± 0.02%	5 kHz < f ≤ 10 kHz : ± 1.5% ± 0.02%	5 kHz < f ≤ 10 kHz : ± 1.5% ± 0.02%	5 kHz < f ≤ 10 kHz : ± 1.5% ± 0.02%	
	10 kHz < f ≤ 50 kHz : ± 30% ± 0.02%	10 kHz < f ≤ 20 kHz : ± 5.0% ± 0.02%	10 kHz < f ≤ 50 kHz : ± 5.0% ± 0.02%	10 kHz < f ≤ 50 kHz : ± 5.0% ± 0.02%	10 kHz < f ≤ 50 kHz : ± 2.0% ± 0.02%	
	- :-	20 kHz < f ≤ 50 kHz : ± 10% ± 0.05%	50 kHz < f ≤ 100 kHz : ± 15% ± 0.05%	50 kHz < f ≤ 100 kHz : ± 10% ± 0.05%	50 kHz < f ≤ 100 kHz : ± 5.0% ± 0.05%	
	- :-	50 kHz < f ≤ 100 kHz : ± 30% ± 0.05%	100 kHz < f ≤ 300 kHz: ± 30% ± 0.05%	100 kHz < f ≤ 300 kHz: ± 15% ± 0.05%	100 kHz < f ≤ 300 kHz: ± 10% ± 0.05%	
	- :-	- :-	- :- 	300 kHz < f ≤ 500 kHz: ± 30% ± 0.05%	300 kHz < f $\leq$ 500 kHz: $\pm$ 15% $\pm$ 0.05% 500 kHz < f < 1 MHz : $\pm$ 30% $\pm$ 0.05%	
Common-Mode Rejection Ratio (CMRR)	150 dB or greater (DC to 1 kHz) 130 dB or greater (1 kHz to 10 kHz) 100 dB or greater (10 kHz to 50 kHz) (effect on output voltage and common mode voltage)	150 dB or greater (DC to 1 kHz) 130 dB or greater (1 kHz to 10 kHz) 100 dB or greater (10 kHz to 100 kHz) (effect on output voltage and common mode voltage)	150 dB or greater (DC to 1 kHz) 135 dB or greater (1 kHz to 10 kHz) 120 dB or greater (10 kHz to 100 kHz) 100 dB or greater (100 kHz to 300 kHz) (effect on output voltage and common mode voltage)	150 dB or greater (DC to 1 kHz) 135 dB or greater (1 kHz to 10 kHz) 115 dB or greater (10 kHz to 100 kHz) 95 dB or greater (100 kHz to 500 kHz) (effect on output voltage and common mode voltage)	140 dB or greater (DC to 1 kHz) 125 dB or greater (1 kHz to 10 kHz) 100 dB or greater (10 kHz to 100 kHz) 80 dB or greater (100 kHz to 1 MHz) (effect on output voltage and common mode voltage)	
Linearity errors (typical)	± 20 ppm	± 20 ppm	± 20 ppm	± 20 ppm	± 20 ppm	
Frequency derating	1800	### 100 1000 A	\$\frac{600}{7700} \frac{1}{\tau} \frac{550}{100} \frac{1}{\tau}	5   400 A   1   1   1   1   1   1   1   1   1	0	
Output voltage	2 mV/A (= 2 V/1000 A)	4 mV/A (= 2 V/500 A)	4 mV/A (= 2 V/500 A)	10 mV/A (= 2 V/200 A)	100 mV/A (= 2 V/20 A)	
Operating temperature and humidity*3	-40° C to 85° C (-40° F to 185° F), 80% RH or less	-40° C to 85° C (-40° F to 185° F), 80% RH or less	-40° C to 85° C (-40° F to 185° F), 80% RH or less	-40° C to 85° C (-40° F to 185° F), 80% RH or less	-40° C to 85° C (-40° F to 185° F), 80% RH or less	
Storage temperature and humidity*3	-40° C to 85° C (-40° F to 185° F), 80% RH or less	-40° C to 85° C (-40° F to 185° F), 80% RH or less	-40° C to 85° C (-40° F to 185° F), 80% RH or less	-40° C to 85° C (-40° F to 185° F), 80% RH or less	-40° C to 85° C (-40° F to 185° F), 80% RH or less	
Withstand voltage	4260 V AC Withstand test current of 1 mA, 50/60 Hz, 1 min., between jaws and cable output terminal	4260 V AC Withstand test current of 1 mA, 50/60 Hz, 1 min., between jaws and cable output terminal	4260 V AC Withstand test current of 1 mA, 50/60 Hz, 1 min., between jaws and cable output terminal	4260 V AC Withstand test current of 1 mA, 50/60 Hz, 1 min., between jaws and cable output terminal	4260 V AC Withstand test current of 1 mA, 50/60 Hz, 1 min., between jaws and cable output terminal	
Standards	Safety: EN 61010, EMC: EN 61326	Safety: EN 61010, EMC: EN 61326	Safety: EN 61010, EMC: EN 61326	Safety: EN 61010, EMC: EN 61326	Safety: EN 61010, EMC: EN 61326	
Cable length	Approx. 3 m (9.84 ft.)	Approx. 3 m (9.84 ft.)	Approx. 3 m (9.84 ft.)	Approx. 3 m (9.84 ft.)	Approx. 3 m (9.84 ft.)	
Dimensions	Approx. 238 W × 116 H × 35 D mm (approx. 9.37 W × 4.57 H × 1.38 D in.)	Approx. 238 W × 116 H × 35 D mm (approx. 9.37 W × 4.57 H × 1.38 D in.)	Approx. 153 W $\times$ 67 H $\times$ 25 D mm (approx. 6.02 W $\times$ 2.64 H $\times$ 0.98 D in.)	Approx. 153 W × 67 H × 25 D mm (approx. 6.02 W × 2.64 H × 0.98 D in.)	Approx. 153 W × 67 H × 25 D mm (Approx. 6.02 W × 2.64 H × 0.98 D in.)	
Weight	Approx. 990 g (34.9 oz.)	Approx. 860 g (30.3 oz.)	Approx. 400 g (14.1 oz.)	Approx. 380 g (13.4 oz.)	Approx. 370 g (13.1 oz.)	

\*1: ± (% of reading + % of range) , range is PW4001 \*2: ± (% of reading + % of full scale) , full scale is rated current of sensor \*3: Non-condensing



### High-accuracy pass-through current sensors

Model	CT6877	A, CT6877A-1	CT6876	A, CT6876A-1	c	T6904A	CT6875	A, CT6875A-1	
Appearance									
Rated current	AC/	DC 2000 A	AC	/DC 1000 A	AC	C/DC 500 A	AC	C/DC 500 A	
Frequency band	DC	c ∼ 1 MHz		A: DC ~ 1.5 MHz -1: DC ~ 1.2 MHz		1A: DC ∼ 4 MHz A-1: DC ∼ 2 MHz		5A: DC ~ 2 MHz -1: DC ~ 1.5 MHz	
Diameter of measurable conductors	Мах. ф 8	80 mm (3.14 in.)	Мах. ф	36 mm (1.41 in.)	Мах. ф	32 mm (1.25 in.)	Мах. ф	36 mm (1.41 in.)	
PW4001 Combined*1	DC	: ± 0.07% ± 0.018%	DC	: ± 0.07% ± 0.018%	DC	: ± 0.055% ± 0.017%	DC	: ± 0.07% ± 0.018%	
Current (I)) , Active power (P)	45Hz ≦ f ≦ 66Hz	: ± 0.07% ± 0.018%	45Hz ≦ f ≦ 66Hz	: ± 0.07% ± 0.018%	45Hz ≦ f ≦ 66Hz	: ± 0.05% ± 0.017%	45Hz ≦ f ≦ 66Hz	: ± 0.07% ± 0.018%	
	DC	: ± 0.04% ± 0.008%	DC	: ± 0.04% ± 0.008%	DC	: ± 0.025% ± 0.007%	DC	: ± 0.04% ± 0.008%	
	DC < f < 16 Hz	: ± 0.1% ± 0.02%	DC < f < 16 Hz	: ± 0.1% ± 0.02%	DC < f < 16 Hz	: ± 0.2% ± 0.02%	DC < f < 16 Hz	: ± 0.1% ± 0.02%	
_	16 Hz ≤ f < 45 Hz 45 Hz ≤ f ≤ 66 Hz	: ± 0.05% ± 0.01% : ± 0.04% ± 0.008%	16 Hz ≤ f < 45 Hz 45 Hz ≤ f ≤ 66 Hz	: ± 0.05% ± 0.01% : ± 0.04% ± 0.008%	16 Hz ≤ f < 45 Hz	: ± 0.1% ± 0.02%	16 Hz ≤ f < 45 Hz 45 Hz ≤ f ≤ 66 Hz	: ± 0.05% ± 0.01% : ± 0.04% ± 0.008%	
Sensor only (amplitude)*2	45 HZ ≤ f ≤ 66 HZ 66 Hz < f ≤ 100 Hz	: ± 0.04% ± 0.008% : ± 0.05% ± 0.01%	45 Hz ≤ f ≤ 66 Hz 66 Hz < f ≤ 100 Hz	: ± 0.04% ± 0.008% : ± 0.05% ± 0.01%	45 Hz ≤ f ≤ 65 Hz 65 Hz < f ≤ 850 Hz	: ± 0.02% ± 0.007% : ± 0.05% ± 0.007%	45 Hz ≤ f ≤ 66 Hz 66 Hz < f ≤ 100 Hz	: ± 0.04% ± 0.008% : ± 0.05% ± 0.01%	
and	100 Hz < f ≤ 500 Hz	: ± 0.1% ± 0.02%	100 Hz < f ≤ 500 Hz	: ± 0.1% ± 0.02%	850 Hz < f ≤ 1 kHz	: ± 0.05% ± 0.007% : ± 0.1% ± 0.01%	100 Hz < f ≤ 500 Hz	: ± 0.1% ± 0.02%	
Sensor only (amplitude)*2	500 Hz < f ≤ 1 kHz	: ± 0.2% ± 0.02%	500 Hz < f ≤ 1 kHz	: ± 0.2% ± 0.02%	1 kHz < f ≤ 5 kHz	: ± 0.4% ± 0.02%	500 Hz < f ≤ 1 kHz	: ± 0.2% ± 0.02%	
	1 kHz < f ≤ 10 kHz	: ± 0.5% ± 0.02%*4	1 kHz < f ≤ 10 kHz	: ± 0.5% ± 0.02%*4	5 kHz < f ≤ 10 kHz	: ± 0.4% ± 0.02%	1 kHz < f ≤ 10 kHz	: ± 0.4% ± 0.02%*4	
	10 kHz < f ≤ 50 kHz	: ± 1.5% ± 0.05%*4	10 kHz < f ≤ 50 kHz	: ± 2% ± 0.05%*4	10 kHz < f ≤ 50 kHz	: ± 1% ± 0.02%	10 kHz < f ≤ 50 kHz	: ± 1.5% ± 0.05%*4	
	50 kHz < f ≤ 100 kHz	: ± 2.5% ± 0.05%*4	50 kHz < f ≤ 100 kHz	: ± 3% ± 0.05%*4	50 kHz < f ≤ 100 kHz	: ± 1% ± 0.05%*5	50 kHz < f ≤ 100 kHz	: ± 2.5% ± 0.05%*4	
	100 kHz < f ≤ 700 kHz	: ± (0.025 × f)% ± 0.05%*4	100 kHz < f ≤ 1 MHz	100 kHz < f ≤ 1 MHz	100 kHz < f ≤ 300 kHz	: ± 2% ± 0.05%*5	100 kHz < f ≤ 1 MHz	: ± (0.025 × f kHz)% ± 0.05%	
	-	1-	-	:-	300 kHz < f ≤ 1 MHz	: ± 5% ± 0.05%*5	-	1-	
Common-Mode Rejection Ratio 140 dB or greater (50/60 Hz) 120 dB or greater (100 kHz)		140 dB or greater (50/60 Hz) 120 dB or greater (100 kHz) (effect on output voltage and common mode voltage)		140 dB or greater (50/60 Hz) 120 dB or greater (100 kHz) (effect on output voltage and common mode voltage)		140 dB or greater (50/60 Hz) 120 dB or greater (100 kHz) (effect on output voltage and common mode voltage			
Linearity errors (typical)	±	10 ppm		± 5 ppm	± 5 ppm			± 5 ppm	
Offset errors (typical)	=	± 5 ppm		± 5 ppm		± 10 ppm		± 5 ppm	
Amplitude errors (typical)	$(100 \sim 1 \text{ kHz}) \pm 0.04$ $(10 \text{ k} \sim 100 \text{ kHz}) \pm 1$	$(10 \sim 100 \text{ Hz}) \pm 0.01\%,$ $4\%$ , $(1 \text{ k} \sim 10 \text{ kHz}) \pm 0.25\%,$ $(100 \text{ k} \sim 300 \text{ kHz}) \pm 2\%,$ $(100 \text{ k} \sim 300 \text{ kHz}) \pm 10\%$	$(100 \sim 1 \text{ kHz}) \pm 0.0$ $(10 \text{ k} \sim 100 \text{ kHz}) \pm 0.0$	$(10 \sim 100 \text{ Hz}) \pm 0.005\%,$ $03\%, (1 \text{ k} \sim 10 \text{ kHz}) \pm 0.2\%$ $1\%, (100 \text{ k} \sim 300 \text{ kHz}) \pm 3\%,$ $\sim 1 \text{ MHz}) \pm 15\%,$		-	$(100 \sim 1 \text{ kHz}) \pm 0.0$ $(20 \text{ k} \sim 100 \text{ kHz}) \pm 0$	$(10 \sim 100 \text{ Hz}) \pm 0.005\%,$ $2\%, (1 \text{ k} \sim 20 \text{ kHz}) \pm 0.08\%,$ $.5\%, (100 \text{ k} \sim 300 \text{ kHz}) \pm 1\%,$ $\sim 1 \text{ MHz}) \pm 5\%$	
Frequency derating	40°C 5.1 ± 60°C (cc. 10°C 10°C 10°C 10°C 10°C 10°C 10°C 10°C	100 1s 100 1M	10		Continuou	A Property of the Control of the Con	25	monute)	
Output voltage	1 mV/A	(=2 V/2000 A)	2 mV/A	A (=2 V/1000 A)	4 mV/	'A (=2 V/500 A)	4 mV/	A (=2 V/500 A)	
Operating temperature and humidity*3	-40° C to 85° C (-40°	F to 185° F), 80% RH or less	-40° C to 85° C (-40°	F to 185° F), 80% RH or less	-10° C to 50° C (-14°	°F to 122°F), 80% RH or less	-40° C to 85° C (-40°	F to 185° F), 80% RH or less	
Storage temperature and humidity*3	-40° C to 85° C (-40°	F to 185° F), 80% RH or less	-40° C to 85° C (-40°	F to 185° F), 80% RH or less	-20° C to 60° C (-4°	F to 140° F), 80% RH or less	-40° C to 85° C (-40°	F to 185° F), 80% RH or less	
Maximum rated voltage to earth		00 V CATIII ient overvoltage: 8000 V		00 V CATIII sient overvoltage: 8000 V		00 V CATIII sient overvoltage: 8000 V		00 V CATIII sient overvoltage: 8000 V	
Standards	Safety: EN 61	010, EMC: EN 61326	Safety: EN 61	1010, EMC: EN 61326	Safety: EN 6	1010, EMC: EN 61326	Safety: EN 6	1010, EMC: EN 61326	
Cable length	CT6877A: ap	oprox. 3 m (9.84 ft.) oprox. 10 m (32.81 ft.)	CT6876A: a CT6876A-1: a	pprox. 3 m (9.84 ft.) pprox. 10 m (32.81 ft.)	CT6904A: approx. 3 m CT6904A-1: approx. 10	n (9.84 ft.) (including relay box)) m (32.81 ft.) (including relay box)	CT6875A: a CT6875A-1: a	approx. 3 m (9.84 ft.) pprox. 10 m (32.81 ft.)	
Dimensions		× 232 H × 112 D mm × 9.13 H × 4.41 D in.)		V × 112 H × 50 D mm V × 4.41 H × 1.97 D in.)		V × 120 H × 52 D mm V × 4.72 H × 2.05 D in.)		V × 112 H × 50 D mm / × 4.41 H × 1.97 D in.)	

<sup>\*1:</sup>  $\pm$  (% of reading + % of range), range is PW4001 \*2:  $\pm$  (% of reading + % of full scale), full scale is rated current of sensor \*3: Non-condensing \*4: When 1 kHz < f  $\leq$  700 kHz (CT6877A-1), 1 kHz < f  $\leq$  1 MHz (CT6876A-1/CT6875A-1), add  $\pm$  (0.005 × f [kHz])% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3, CT6904A-1), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), CT6904A-1), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), CT6904A-1), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), CT6904A-1), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), CT6904A-1), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A-3), add  $\pm$  (0.015 × f)% of reading to amplitude accuracy \*5: When 50 kHz < f  $\leq$  1 MHz (CT6904A



# High-accuracy pass-through current sensors

Product warranty period: 3 year Guaranteed accuracy period: 1 year

Model		CT68	73, CT6873-01	C.	Г6863-05	CT68	72, CT6872-01	СТ	6862-05
Appearance									
Rated current		2	00 A AC/DC	20	0 A AC/DC	5	50 A AC/DC	50	A AC/DC
Frequency band		D	C to 10 MHz	DC	to 500 kHz	D	C to 10 MHz	DC	to 1 MHz
Diameter of measu	rable conductors	Max. d	24 mm (0.94 in.)	Мах. ф	24 mm (0.94 in.)	Max. d	24 mm (0.94 in.)	Мах. ф 2	24 mm (0.94 in.)
PW4001 Comb	oined*1 Active power (P)	DC 45Hz ≦ f ≦ 66Hz	: ± 0.06% ± 0.012% : ± 0.06% ± 0.017%		ıracy + Sensor accuracy	DC 45Hz ≦ f ≦ 66Hz	: ± 0.06% ± 0.012% : ± 0.06% ± 0.017%		racy + Sensor accuracy
Accuracy Sensor only (	(amplitude)*2	DC < f \le 16 Hz  16 Hz < f \le 45 Hz  45 Hz < f \le 66 Hz  45 Hz < f \le 66 Hz  66 Hz < f \le 100 Hz  100 Hz < f \le 500 Hz  500 Hz < f \le 30 kHz  3 kHz < f \le 10 kHz  10 k Hz < f \le 10 MHz	$\begin{array}{l} : \pm \ 0.03\% \pm 0.002\% \\ : \pm \ 0.1\% \pm 0.01\% \\ : \pm \ 0.05\% \pm 0.01\% \\ : \pm \ 0.03\% \pm 0.007\% \\ : \pm \ 0.04\% \pm 0.01\% \\ : \pm \ 0.05\% \pm 0.01\% \\ : \pm \ 0.1\% \pm 0.01\% \\ : \pm \ 0.01\% \pm 0.05\% \\ \end{array}$	DC		DC DC < f \le 16 Hz 16 Hz < f \le 45 Hz 45 Hz < f \le 66 Hz 66 Hz < f \le 100 Hz 100 Hz < f \le 500 Hz 500 Hz < f \le 10 kHz 10 kHz < f \le 10 kHz 10 kHz < f \le 10 kHz	$\begin{array}{l} : \pm \ 0.03\% \pm 0.002\% \\ : \pm \ 0.1\% \pm 0.01\% \\ : \pm \ 0.05\% \pm 0.01\% \\ : \pm \ 0.03\% \pm 0.007\% \\ : \pm \ 0.04\% \pm 0.01\% \\ : \pm \ 0.06\% \pm 0.01\% \\ : \pm \ 0.1\% \pm 0.01\% \\ : \pm \ 0.1\% \pm 0.01\% \\ : \pm \ 0.1\% \pm 0.01\% \\ : \pm \ 0.15\% \pm 0.02\% \\ : \pm \ (0.012 \times f \ kHz)\% \pm 0.05\% \end{array}$		$\begin{array}{l} : \pm 0.05\% \pm 0.01\% \\ : \pm 0.10\% \pm 0.02\% \\ : \pm 0.05\% \pm 0.01\% \\ : \pm 0.2\% \pm 0.02\% \\ : \pm 0.7\% \pm 0.02\% \\ : \pm 10.7\% \pm 0.02\% \\ : \pm 1\% \pm 0.02\% \\ : \pm 1\% \pm 0.02\% \\ : \pm 2\% \pm 0.05\% \\ : \pm 5\% \pm 0.05\% \end{array}$
Common-Mode Rejection Ratio (CMRR)  150 dB or greater (DC to 1 kHz)  140 dB or greater (1 kHz to 10 kHz)  120 dB or greater (10 kHz to 100 kHz)  100 dB or greater (10 kHz to 1 MHz)  (effect on output voltage and common mode voltage		0.05% f.s. or less (1000 V rms, DC to 100 Hz)		- 150 dB or greater (DC to 1 kHz) 140 dB or greater (1 kHz to 10 kHz) 120 dB or greater (10 kHz to 100 kHz) 100 dB or greater (100 kHz to 1 MHz) (effect on output voltage and common mode voltage)		700 kHz < f < 1 MHz : ± 30% ± 0.05% 0.05% f.s. or less (1000 V rms, DC to 100 Hz)			
Linearity errors (typ	oical)		± 2 ppm	-		± 2 ppm			-
Offset errors (typical	al)		± 5 ppm	- ± 5 ppm			-		
(DC) ± 7 ppm, (10 to 500 Hz) ± 0.005%, (500 Hz-3 kHz) ± 0.01%, (30 k to 100 kHz) ± 0.01%, (30 k to 100 kHz) ± 0.4%, (100 k to 400 kHz) ± 1%, (400 kHz to 1 MHz) ± 3%		-		(DC) ± 7 ppm, (10 to 100 Hz) ± 0.005%, (100 Hz to 1 kHz) ± 0.01%, (1 k to 50 kHz) ± 0.1%, (50 k to 100 kHz) ± 0.3%, (100 k to 300 kHz) ± 1%, (300 kHz to 1 MHz) ± 3%			-		
Frequency deratinç	g	500 400 A (	C (continuous)	W 4 400	100 1k 10k 100k 1M	120	(1 minuta) (continuous) (continuous) (continuous) (continuous) (continuous)	Mul 120 Mul 100 Mul 10	100 1k 10k 100k 1M Frequency (FU)
Output voltage		10 mV	//A (= 2 V/200 A)	10 mV/	A (= 2 V/200 A)	40 m	V/A (= 2 V/50 A)	40 mV/	A (= 2 V/50 A)
Operating tempera	ture and humidity*4	-40° C to 85° C (-40	°F to 185°F), 80% RH or less	-30° C to 85° C (-22°	F to 185° F), 80% RH or less	-40° C to 85° C (-40° F to 185° F), 80% RH or less		-30° C to 85° C (-22°	F to 185° F), 80% RH or less
Storage temperatur	re and humidity*4	-40° C to 85° C (-40	°F to 185°F), 80% RH or less	-30° C to 85° C (-22°	F to 185° F), 80% RH or less	-40° C to 85° C (-40	o° F to 185° F), 80% RH or less	-30° C to 85° C (-22°	F to 185° F), 80% RH or less
Maximum rated vol	Itage to earth		000 V CATIII nsient overvoltage: 8000 V		OC CATIII (50/60 Hz) sient overvoltage: 8000 V		000 V CATIII nsient overvoltage: 8000 V		C CAT III (50/60 Hz) ient overvoltage: 8000 V
Standards		Safety: EN 6	1010, EMC: EN 61326	Safety: EN 61010, EMC: EN 61326		Safety: EN 6	61010, EMC: EN 61326	Safety: EN 61	010, EMC: EN 61326
Cable length			pprox. 3 m (9.84 ft.) approx. 10 m (32.81 ft.)	Approx	c. 3 m (9.84 ft.)		approx. 3 m (9.84 ft.) approx. 10 m (32.81 ft.)	Approx	. 3 m (9.84 ft.)
Dimensions		(approx. 2.76 \	V × 110 H × 53 D mm V × 4.33 H × 2.09 D in.)		X 100 H X 53 D mm X 3.94 H X 2.09 D in.)	(approx. 2.76 \	N × 110 H × 53 D mm N × 4.33 H × 2.09 D in.)		/ × 100 H × 53 D m × 3.94 H × 2.09 D in.)
Weight	CT6873: approx. 370 g (13.1 oz.) CT6873-01: approx. 690 g (24.3 oz.)			Approx.	350 g (12.3 oz.)		prox. 370 g (13.1 oz.) pprox. 690 g (24.3 oz.)	Approx.	340 g (12.0 oz.)

<sup>\*1: ± (%</sup> of reading + % of range), range is PW4001 \*2: ± (% of reading + % of full scale), full scale is rated current of sensor \*3: Figures for CT6862-05 and CT6863-05 reflect effects of common-mode voltage. \*4: Non-condensing



# General use clamp sensor

Product warranty period: 3 year Guaranteed accuracy period: 1 year

Model	9272-05
Appearance	
Rated current	20 A AC, 200 A AC (2 range)
Frequency band	1 Hz ∼ 100 kHz
Diameter of measurable conductors	φ 46 mm or less
Accuracy (amplitude) 士 (% of reading + % of full scale)	$\begin{array}{lll} 1 \text{ Hz} \le f < 5 \text{ Hz} & : \pm 2.0\% \pm 0.10\% \\ 5 \text{ Hz} \le f < 10 \text{ Hz} & : \pm 1.0\% \pm 0.05\% \\ 10 \text{ Hz} \le f < 45 \text{ Hz} & : \pm 0.5\% \pm 0.02\% \\ 45 \text{ Hz} \le f \le 66 \text{ Hz} & : \pm 0.3\% \pm 0.01\% \\ 66 \text{ Hz} < f \le 500 \text{ Hz} & : \pm 0.5\% \pm 0.02\% \\ 500 \text{ Hz} < f \le 1 \text{ kHz} & : \pm 0.5\% \pm 0.02\% \\ 1 \text{ kHz} < f \le 5 \text{ kHz} & : \pm 1.0\% \pm 0.05\% \\ 5 \text{ kHz} < f \le 10 \text{ kHz} & : \pm 2.5\% \pm 0.10\% \\ 10 \text{ kHz} < f \le 20 \text{ kHz} & : \pm 5\% \pm 0.1\% \\ 20 \text{ kHz} < f \le 50 \text{ kHz} & : \pm 5\% \pm 0.1\% \\ 50 \text{ kHz} < f \le 100 \text{ kHz} & : \pm 5\% \pm 0.1\% \\ 50 \text{ kHz} < f \le 100 \text{ kHz} & : \pm 30\% \pm 0.1\% \\ \end{array}$
Frequency derating	200 A range 200 A
Output voltage	20 A range: 100 mV/A (= 2 V/20 A) 200 A range: 10 mV/A (= 2 V/200 A)
Operating temperature and humidity*1	0° C to 50° C (32° F to 122° F), 80% RH or less
Storage temperature and humidity*1	-10° C to 60° C (14° F to 140° F), 80% RH or less
Withstand voltage	AC 600 V CATIII (50/60 Hz) anticipated transient overvoltage: 6000 V
Standards	Safety: EN 61010, EMC: EN 61326 Class A
Cable length	Approx. 3 m (9.84 ft.)
Dimensions	Approx. 78 W × 188 H × 35 D mm (approx. 3.07 W × 7.40 H × 1.38 D in.)
Weight	Approx. 450 g (15.9 oz.)

<sup>\*1:</sup> Non-condensing

# Direct-wiring type high-accuracy current sensors

Product warranty period: 3 year Guaranteed accuracy period: 1 year

Мо	del	PW9100A-3,	PW9100A-4		
Appearance		April April April	in in in in		
Rat	ed current	50 A A	AC/DC		
Fre	quency band	DC to 3	.5 MHz		
Ме	asurement terminals	Isolated input Terminal block (with sa	, DCCT input fety cover), M6 screws		
	PW4001 Combined <sup>*1</sup> Current (I)) , Active power (P)	45Hz ≦ f ≦ 66Hz	: ± 0.05% ± 0.017% : ± 0.05% ± 0.015%		
Accuracy	Sensor only (amplitude) <sup>2</sup>	DC < f < 30 Hz 30 Hz ≤ f < 45 Hz 45 Hz ≤ f ≤ 65 Hz 65 Hz < f ≤ 500 Hz 500 Hz < f ≤ 1 kHz 1 kHz < f ≤ 5 kHz 5 kHz < f ≤ 20 kHz 20 kHz < f ≤ 50 kHz 50 kHz < f ≤ 100 kHz 100 kHz < f ≤ 300 kHz 300 kHz < f ≤ 700 kHz 100 kHz < f ≤ 100 kHz	$\begin{array}{l} \pm 0.02\% \pm 0.007\% \\ \vdots \pm 0.1\% \pm 0.02\% \\ \vdots \pm 0.1\% \pm 0.02\% \\ \vdots \pm 0.1\% \pm 0.005\% \\ \vdots \pm 0.1\% \pm 0.01\% \\ \vdots \pm 0.1\% \pm 0.01\% \\ \vdots \pm 0.1\% \pm 0.02\% \\ \vdots \pm 1\% \pm 0.05\% \\ \vdots \pm 5\% \pm 0.05\% \\ \vdots \pm 5\% \pm 0.05\% \\ \vdots \pm 1\% \pm 0.05\% \\ \end{array}$		
Effe	ects of common mode voltage	120 dB or greater (50/60 Hz, 100 kHz) (effect on output voltage and common mode voltage)			
Frequency derating		Guaranteed accuracy range  Countries of the country range of the country range of the country range of the country range of the countries of t	30 MHz/80 A  1442/30 A  1 MHz/10 A  1 MHz/10 A  1 MHz/10 A		
Ou	tput voltage	40 mV/A (=	= 2 V/50 A)		
Operating temperature and humidity <sup>3</sup>		0° C to 40° C (32° F to 104° F), 80% RH or less			
Storage temperature and humidity*3		-10° C to 50° C (14° F to 122° F), 80% RH or less			
Withstand voltage		600 V CATIII, 1000 V CATII anticipated transient overvoltage: 6000 V			
Sta	ndards	Safety: EN 61010, EMC: EN 61326 Class A			
Cal	ble length	Approx. 0.8	m (2.62 ft.)		
Din	nensions	Approx. 430 W × 88 H × 260 D mm (approx. 16.9 W × 3.46 H × 10.23 D in.)			
eig	ht	PW9100A-3: approx PW9100A-4: approx			

<sup>\*1:</sup>  $\pm$  (% of reading + % of range), range is PW4001

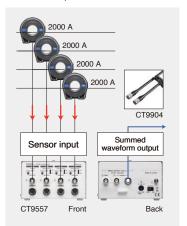
<sup>\*2:</sup>  $\pm$  (% of reading + % of full scale) , full scale is rated current of sensor

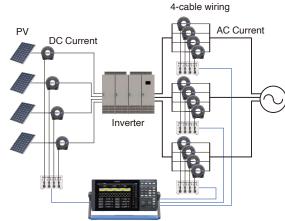
<sup>\*3:</sup> Non-condensing



# **Measure Large Currents of up to 8000 A**

**The Sensor Unit CT9557** adds and outputs current sensor output from multi-wire lines. With the PW4001, the CT9557 can be used to accurately measure large currents of up to 8000 A (on a 4-wire line).





#### CT9557 specifications

Connectable current	Current sensors are listed			
sensor	on p. 26 - p. 29			
	DC : ± 0.06% ± 0.03%			
Summed waveform	to 1 kHz : ± 0.06% ± 0.03%			
output accuracy	to 10 kHz : ± 0.10%. ± 0.03%			
± (% of reading + % of full	to 100 kHz : ± 0.20% ± 0.10%			
scale)	to 300 kHz : ± 1.0% ± 0.20%			
scale)	to 700 kHz : ± 5.0% ± 0.20%			
	to 1 MHz : ± 10.0% ± 0.50%			
Operating temperature and	-10° C to 50° C (14° F to 122° F),			
humidity	80% RH or less			
Power supply	100 V to 240 V AC (50 Hz/60 Hz)			
Output connector	HIOKI ME15W (male connector)			
Dimensions (W x H x D)	Approx. 116 × 67 × 132 mm			
Difficusions (W X 11 X D)	(approx. 4.57. × 2.64. × 5.20 in.)			
Weight	Approx. 420 g (14.8 oz.)			
Included accessories	AC ADAPTER Z1002, Power cord			

Wiring	Current	Using sensors
Single-cable or bundled	1000 A	CT6876A CT6846A
wiring	2000 A	CT6877A
2-cable wiring	2000 A	CT9557+CT6876A×2/ CT9557+CT6846A×2
wiilig	4000 A	CT9557+CT6877A×2
3-cable	3000 A	CT9557+CT6876A×3/ CT9557+CT6846A×3
wiring	6000 A	CT9557+CT6877A×3/
4-cable	4000 A	CT9557+CT6876A×4/ CT9557+CT6846A×4
wiring	8000 A	CT9557+CT6877A×4



**SENSOR UNIT CT9557** 

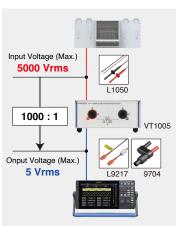


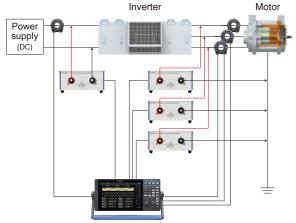
Option
CONNECTION CABLE CT9904
Cable length: 1 m (3.28 ft)

CT9904 required to connect to PW4001.

# Measure High Voltages of up to 5000 V

The AC/DC High Voltage Divider VT1005 divides and outputs voltages of up to 5000 V. With the PW4001, the VT1005 can accurately measure high voltages of up to 5000 V.

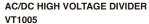


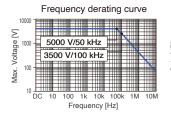


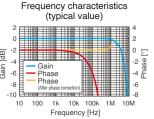
#### VT1005 specifications

Maximum rated voltage	5000 V rms, ± 7100 V peak (Provided this falls within the frequency derating curve illustrated)
Maximum rated voltage (line-to-ground)	No measurement category: 5000 V AC/DC (7100 V peak, Anticipated transient overvoltage 0 V) Measurement category II: 2000 V AC/DC (Anticipated transient overvoltage 12000 V) Measurement category III: 1500 V AC/DC (Anticipated transient overvoltage 10000 V)
Measurement accuracy	$\pm$ 0.08% (DC), $\pm$ 0.04% (50 Hz/60 Hz), $\pm$ 0.17% (50 kHz)
Frequency flatness	Band where amplitude falls within ± 0.1% range: 200 kHz (typical) Band where phase falls within ± 0.1° range: 500 kHz (typical) <sup>(*5)</sup>
Measurement bandwidth	DC to 4 MHz (Amplitude and phase accuracy specified up to 1 MHz)
Voltage dividing ratio	1000 : 1
Common-mode voltage rejection ratio (CMRR)	50 Hz/60 Hz: 90 dB (typical), 100 kHz: 80 dB (typical)
Operating temperature and humidity range	-10° C to 50° C (14° F to 122° F), 80% RH or less (non-condensing)
Power supply	100 V to 240 V AC (50/60 Hz)
Dimensions (W x H x D)	Approx. 195.0 × 83.2 × 346.0 mm (approx.7.68 × 3.28 × 13.62 in.)
Weight	Approx. 2.2 kg (77.6 oz.)
Measurement method	Differential input
Included accessories	- L1050-01 Voltage Cord (1.6 m/5.25 ft) - L9217 Connection Cord (insulated BNC, 1.6 m/ 5.25 ft) - 9704 Conversion Adapter (insulated-female BNC-to-banana plug) - Power cord











#### Model: POWER ANALYZER PW4001

Model No, (Order Code)	D/A output	Motor analysis	DC power operation( (10.5 to 28 V DC))
PW4001-01	_	_	_
PW4001-02	✓	_	_
PW4001-03	_	✓	_
PW4001-04	_	_	✓
PW4001-05	✓	✓	✓



Accessories: Startup guide X 1, power cord X 1, USB cable X 1, D-sub 25-pin connector X 1, DC power supply connector (PW4001-04, -05)

# Current measurement options (High accuracy: clamp type)

Model No. (Order Code)	Model	Rated Current	Frequency band	Cable length
CT6834	AC/DC CURRENT PROBE	500 A rms	DC to 50 kHz	5 m
CT6834-01	AC/DC CURRENT PROBE	500 A rms	DC to 50 kHz	10 m
CT6833	AC/DC CURRENT PROBE	200 A rms	DC to 50 kHz	5 m
CT6833-01	AC/DC CURRENT PROBE	200 A rms	DC to 50 kHz	10 m
CT6831	AC/DC CURRENT PROBE	20 A rms	DC to 100 kHz	4.2 m
CT6830	AC/DC CURRENT PROBE	2 A rms	DC to 100 kHz	4.2 m
CT6846A	AC/DC CURRENT PROBE	1000 A rms	DC to 100 kHz	3 m
CT6845A	AC/DC CURRENT PROBE	500 A rms	DC to 200 kHz	3 m
CT6844A	AC/DC CURRENT PROBE	500 A rms	DC to 500 kHz	3 m
CT6843A	AC/DC CURRENT PROBE	200 A rms	DC to 700 kHz	3 m
CT6841A	AC/DC CURRENT PROBE	20 A rms	DC to 2 MHz	3 m
9272-50	CLAMP ON SENSOR	AC 20 A/200 A rms	DC to 100 kHz	3 m

#### Current measurement options (High accuracy: pass-through, direct connection type)

Model No. (Order Code)	Model	Rated Current	Frequency band	Cable length or number of channels
CT6877A	AC/DC CURRENT SENSOR	2000 A rms	DC to 1 MHz	3 m
CT6877A-1	AC/DC CURRENT SENSOR	2000 A rms	DC to 1MHz	10 m
CT6876A	AC/DC CURRENT SENSOR	1000 A rms	DC to 1.5 MHz	3 m
CT6876A-1	AC/DC CURRENT SENSOR	1000 A rms	DC to 1.2 MHz	10 m
CT6904A	AC/DC CURRENT SENSOR	500 A rms	DC to 4 MHz	3 m
CT6875A	AC/DC CURRENT SENSOR	500 A rms	DC to 2 MHz	3 m
CT6875A-1	AC/DC CURRENT SENSOR	500 A rms	DC to 1.5 MHz	10 m
CT6873	AC/DC CURRENT SENSOR	200 A rms	DC to 10 MHz	3 m
CT6873-01	AC/DC CURRENT SENSOR	200 A rms	DC to 10 MHz	10 m
CT6863-05	AC/DC CURRENT SENSOR	200 A rms	DC to 500 kHz	3 m
CT6872	AC/DC CURRENT SENSOR	50 A rms	DC to 10 MHz	3 m
CT6872-01	AC/DC CURRENT SENSOR	50 A rms	DC to 10 MHz	10 m
CT6862-05	AC/DC CURRENT SENSOR	50 A rms	DC to 1 MHz	3 m
PW9100A-3	AC/DC CURRENT BOX	50 A rms	DC to 3.5 MHz	3 ch
PW9100A-4	AC/DC CURRENT BOX	50 A rms	DC to 3.5 MHz	4 ch

#### Current measurement options (Standard Sensor)

Model No. (Order Code)	Model	Rated Current	Frequency band	cable length
CT7742**	AC/DC AUTO ZERO CURRENT SENSOR	2000 A rms	DC to 5 kHz	2.5 m
CT7642**	AC/DC CURRENT SENSOR	2000 A rms	DC to 10 kHz	2.5 m
CT7044**	AC FLEXIBLE CURRENT SENSOR (Φ100 mm(3.94 in.) )	6000 A rms	10 Hz to 50 kHz	2.5 m
CT7045**	AC FLEXIBLE CURRENT SENSOR (Φ180 mm(7.09 in.) )	6000 A rms	10 Hz to 50 kHz	2.5 m
CT7046**	AC FLEXIBLE CURRENT SENSOR (Φ254mm(10.00 in.))	6000 A rms	10 Hz to 50 kHz	2.5 m

<sup>\*\*</sup> CONVERSION CABLE CT9920 is required to connect to the PW4001.



Required to connect PW4001 to the current sensor with HIOKI PL14 on the output connector.  $\label{eq:higher_potential}$ 

[Applicable products] CT7742, CT7642, CT7044, CT7045, CT7046



CONVERSION CABLE Cable length: 1 m (3.28 ft) Required to connect the summing waveform output terminal of CT9557 to PW4001.

[Applicable products] CT9557

<sup>•</sup> The separately sold voltage cords and current sensors are required for taking measurements.

<sup>•</sup> Specify whether to include the Motor Analysis, D/A Output, and DC power operation options upon order for factory installation.



#### Voltage measurement options

1	L1025	VOLTAGE CORD	1500 V DC CATII, 1 A, 1000 V CATIII , 1 A banana-banana (red, black, 1 each), alligator clip, approx. 3 m (9.84 ft.) length
2	L9438-50	VOLTAGE CORD	1000 V CATIII, 10 A, 600 V CATIV, 10 A banana-banana (red, black, 1 each), alligator clip, spiral tube, approx. 3 m (9.84 ft.) length
3	L1000	VOLTAGE CORD	1000 V CATIII, 10 A, 600 V CATIV, 10 A banana-banana (red, yellow, blue, gray, 1 each, black $\times$ 4), alligator clip, approx. 3 m (9.84 ft.) length
4	L9257	CONNECTION CORD	1000 V CATIII, 10 A, 600 V CATIV, 10 A banana-banana (red, black, 1 each), alligator clip, approx. 1.2 m (3.94 ft.) length
5	L1021-01	PATCH CORD	1000 V CATIII, 10 A, 600 V CATIV, 10 A for branching voltage input, banana branch to banana clip (red $\times$ 1), 0.5 m (1.64 ft.) length
6	L1021-02	PATCH CORD	1000 V CATIII, 10 A, 600 V CATIV, 10 A for branching voltage input, banana branch to banana clip (black × 1), 0.5 m (1.64 ft.) length
7	L9243	GRABBER CLIP	1000 V CATII, 1 A, (red, black, 1 each)
8	L4940	CONNECTION CORD	1000 V CATIII, 10 A, 600 V CATIV, 10 A banana-banana (red, black, 1 each), approx. 1.5 m (4.92 ft.) length
9	L4935	ALLIGATOR CLIP SET	1000 V CATIII, 10 A, 600 V CATIV, 10 A, (red, black, 1 each)
10	VT1005	AC/DC HIGH VOLTAGE DIVIDER	Voltage divider up to 5000 V and output to PW4001 Accessories: 9704, L1050-01(1.6m), L9217(1.6m)
11	L1050-01, -03	VOLTAGE CORD	For VT1005, 1.6 m (L1050-01), 3 m (L1050-03)
12	L9217-01, -02	CONNECTION CORD	For VT1005 connection, insulated BNC, CAT II 600 V, 0.2 A, CAT III 300 V, 0.2 A, 3.0 m(L9217-01), 10.0 m(L9217-02)

#### Connection options

	L9217	CONNECTION CORD	For motor analysis input, insulated BNC, CAT II 600 V, 0.2 A, CAT III 300 V, 0.2 A, 1.6 m
14		CONNECTION CABLE	For BNC synchronization, metal BNC by metal BNC, 1.5 m (4.92 ft.) length
15	9713-01	CAN CABLE	One end terminating in bare wires, 2 m (6.56 ft.) length
16	CT9902	EXTENSION CABLE	For extension of current sensor cable, ME15W-ME15W, 5 m (16.40 ft.) length
17	CT9557	SENSOR UNIT	Adds output waveforms from up to 4 current sensors to 1 channel and outputs it to the PW4001.
18	CT9904	CONNECTION CORD	Cable length 1 m; required in order to connect the CT9557's added waveform output terminal to the PW4001.

### Others

19	SP7001-95	NON-CONTACT CAN SENSOR	Acquires CAN or CAN FD signals, simply by pinching probes over wire insulation. It connects to the CAN connector of the PW4001, supports CAN or CAN FD communication, and can be powered via a USB connector.
20	L3000	D/A OUTPUT CABLE	D-sub 25-pin by BNC (male) 20-channel conversion cable
2	Z5200	BNC TERMINAL BOX	D-sub 25-pin by BNC (female) 20-channel conversion box
	C4001	CARRYING CASE	Hard-trunk type, with casters
	Z5302	RACKMOUNT FITTINGS	For EIA standard rack
24	Z5303	RACKMOUNT FITTINGS	For JIS standard rack

